

DSC 40B

Lecture 18 : BFS



Graph Search Strategies

How do we:

- determine if there is a path between two nodes?
- check if graph is connected?
- count connected components?

Search Strategies

- A **search strategy** is a procedure for *exploring* a graph.
- Different strategies are useful in different situations.

Node Statuses

- At any point during a search, a node is in exactly one of three states:
 - **visited**
 - **pending** (discovered, but not yet visited)
 - **undiscovered**

Rules

- At every step, next **visited** node chosen from among **pending** nodes.
- When a node is marked as **visited**, all of its neighbors have been marked as **pending**.

Choosing the next Node

- How to choose among **pending** nodes?
 - **Idea 1**: Visit *newest* pending (**depth-first search**).
 - **Idea 2**: Visit *oldest* pending (**breadth-first search**).

Main Idea

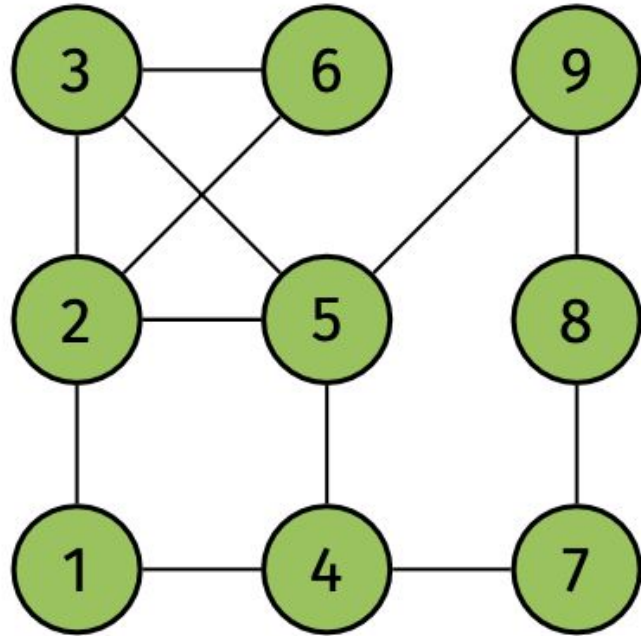
- **Depth-first search** (DFS) and **breadth-first search** (BFS) each discover *different* properties of the graph.
- For example, we'll see that BFS is useful for finding **shortest paths** (DFS in general is not).

Breadth-First Search

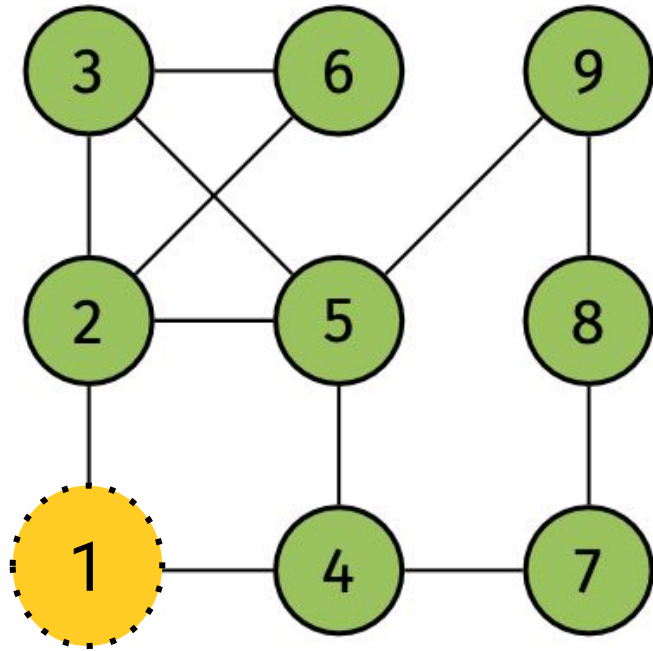
Breadth-First Search

- At every step:
 - Visit **oldest pending** node.
 - Mark its **undiscovered** neighbors as **pending**.
- **Convention:** in this class, neighbors produced in **sorted** order.
 - In general, the order in which a node's neighbors produced is arbitrary.

Example



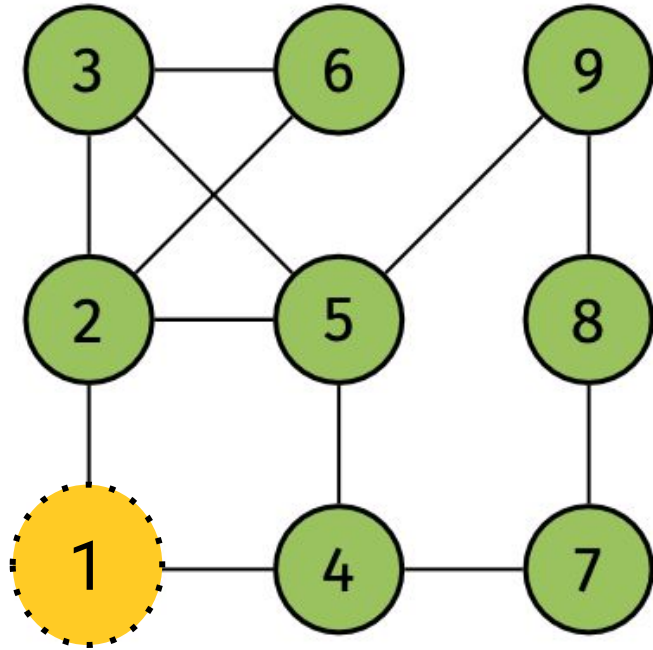
Example



Before iterating.

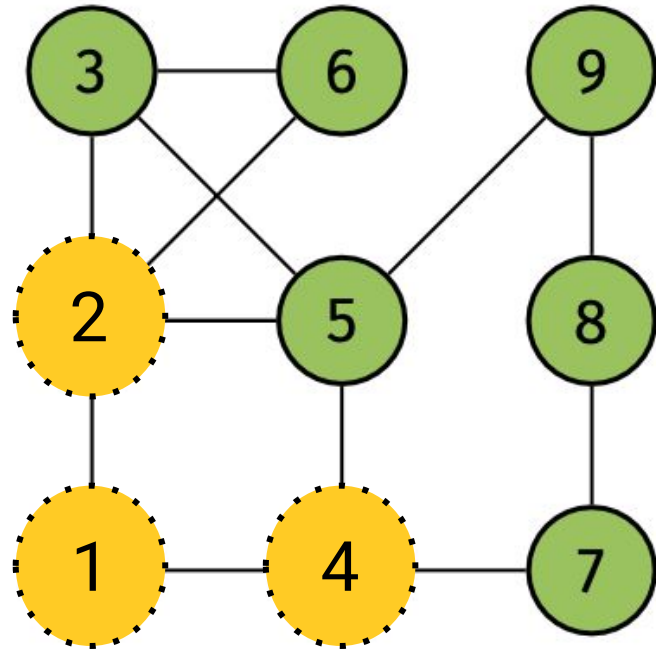
pending = [1]

Example



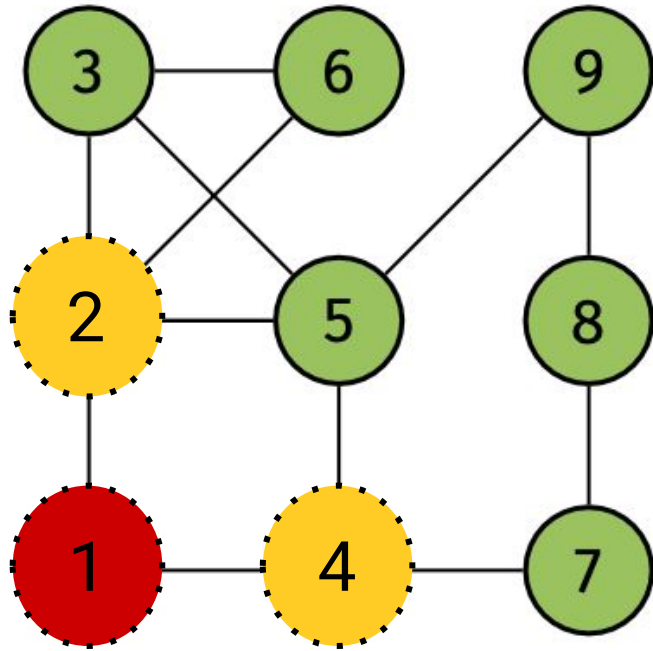
pending = [1, 2, 4]

Example



pending = [1, 2, 4]

Example



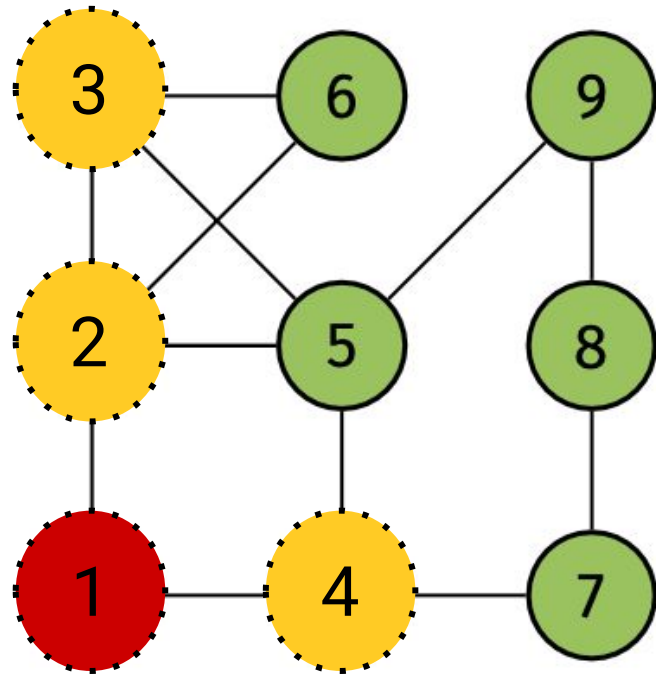
After 1st iteration.

pending = [2, 4]

states:

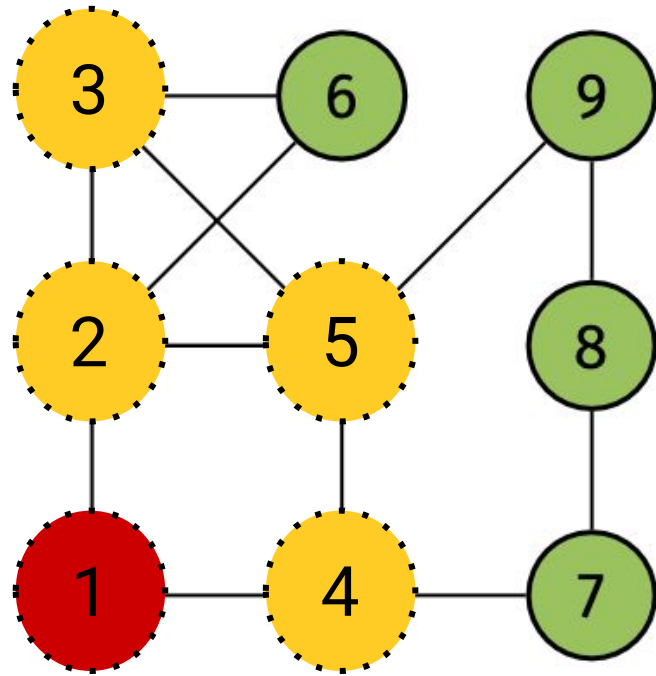
- **visited**
- **pending** (discovered, but not yet visited)
- **undiscovered**

Example



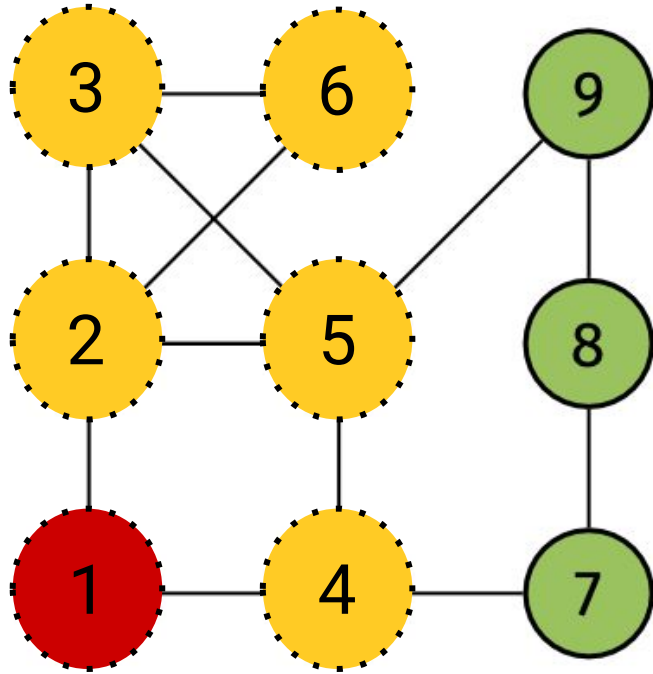
pending = [2, 4, 3]

Example



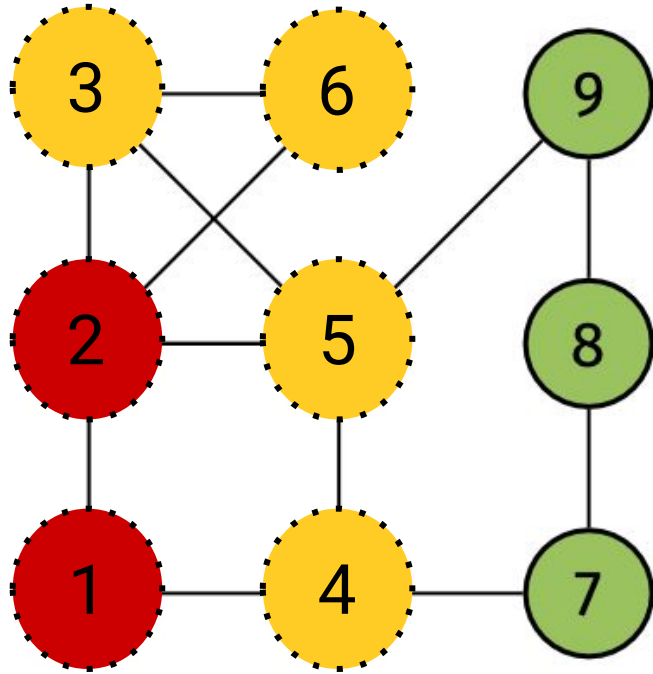
pending = [2, 4, 3, 5]

Example



pending = [2, 4, 3, 5, 6]

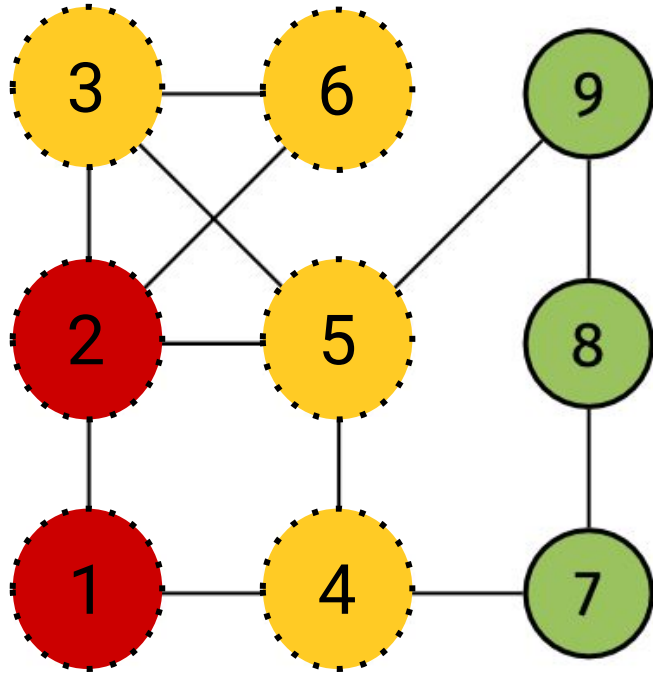
Example



After 2nd iteration.

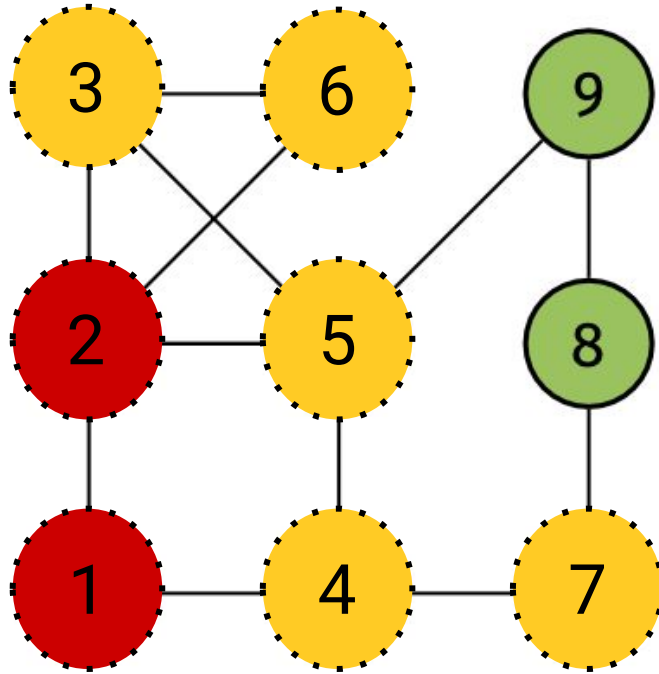
pending = [4, 3, 5, 6]

Example



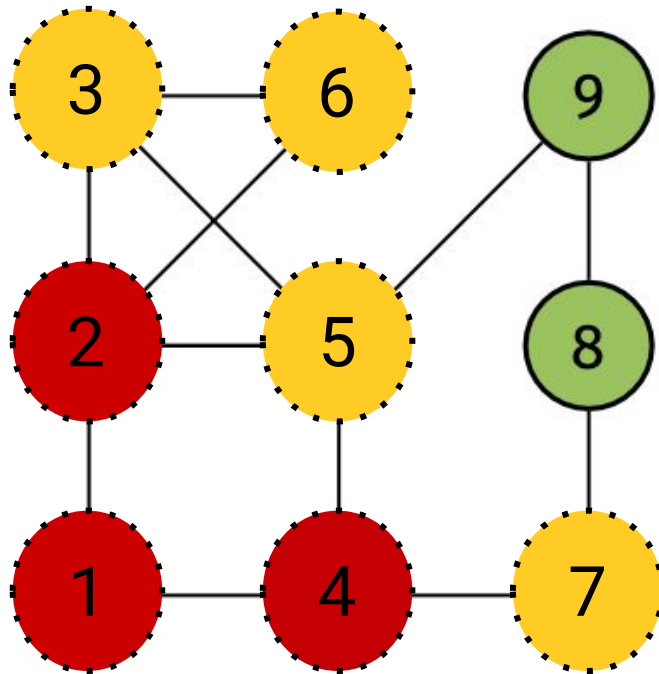
pending = [4, 3, 5, 6, ?]

Example



pending = [4, 3, 5, 6, 7]

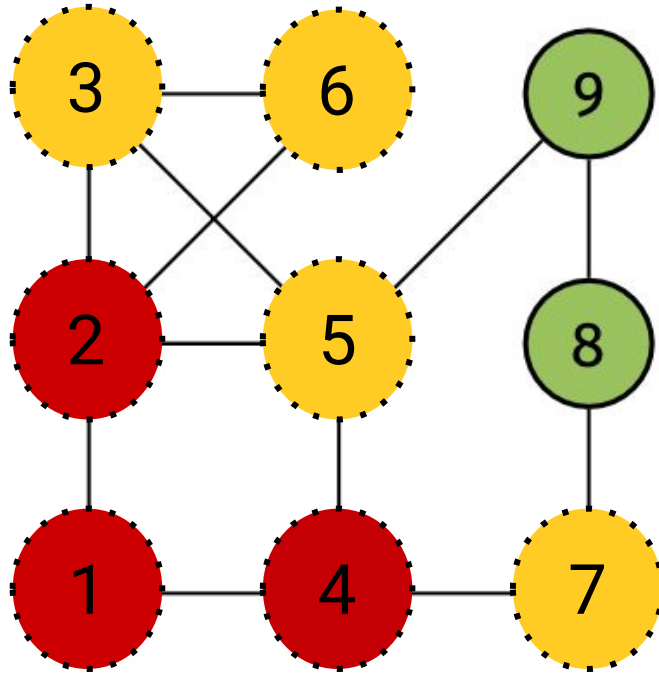
Example



After 3rd iteration

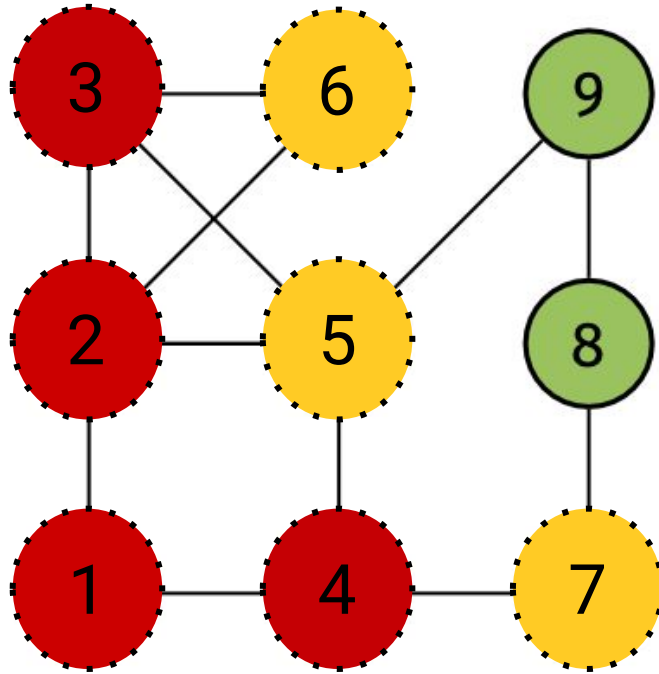
pending = [3, 5, 6, 7]

Example



pending = [3, 5, 6, 7, ?]

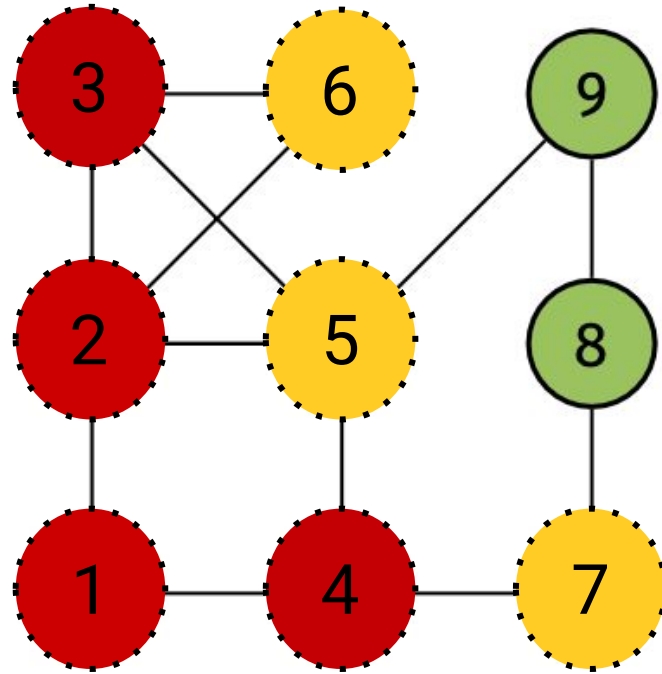
Example



After 4th iteration

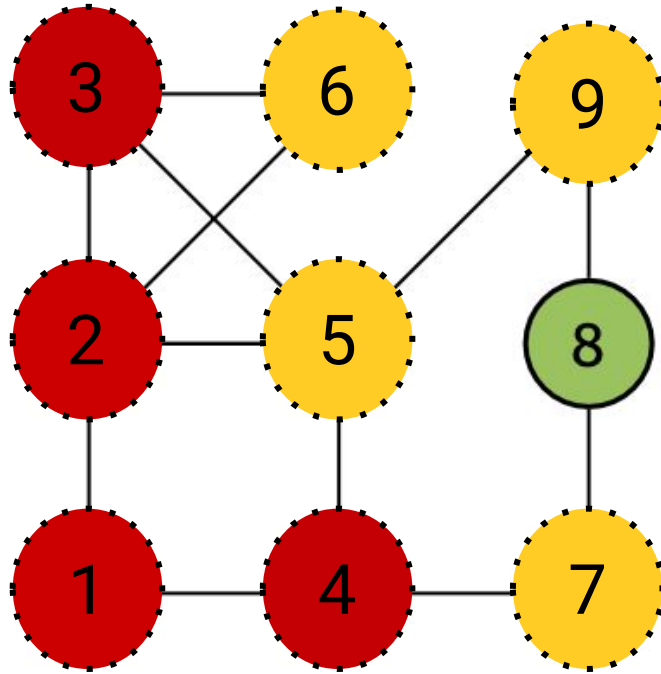
pending = [5, 6, 7]

Example



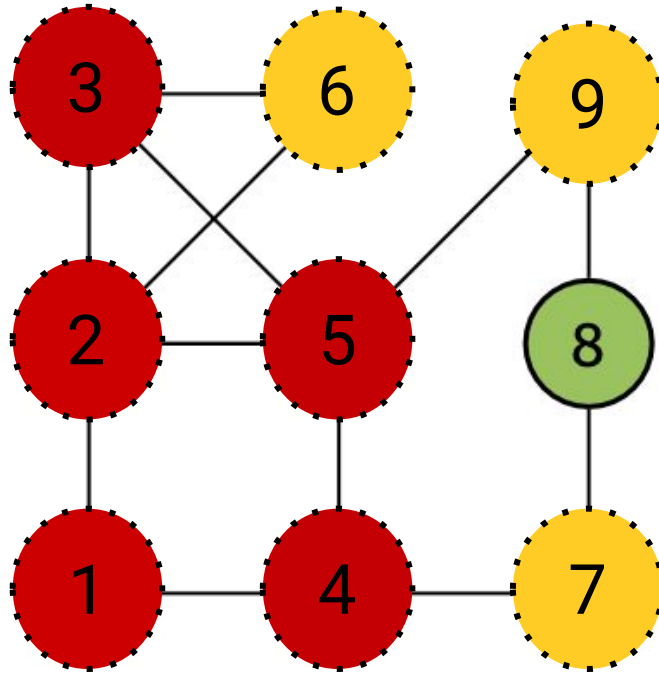
pending = [5, 6, 7, ?]

Example



pending = [5, 6, 7, 9]

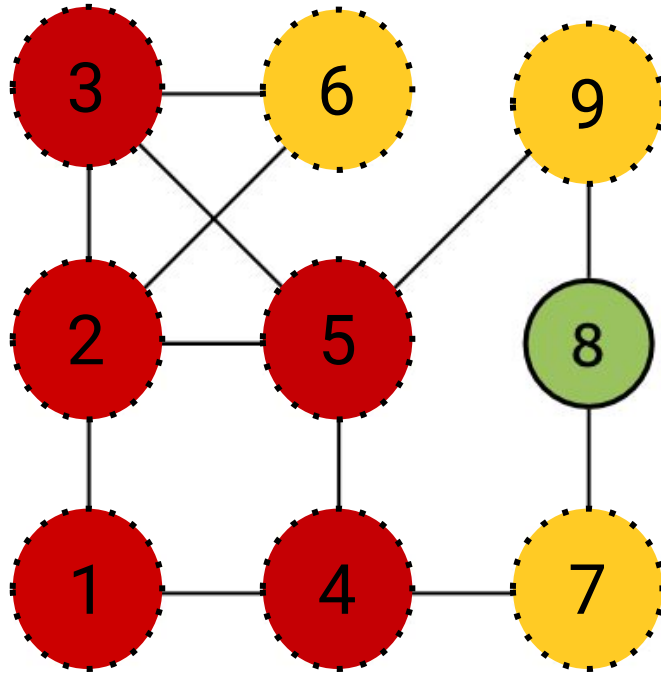
Example



After 5th iteration

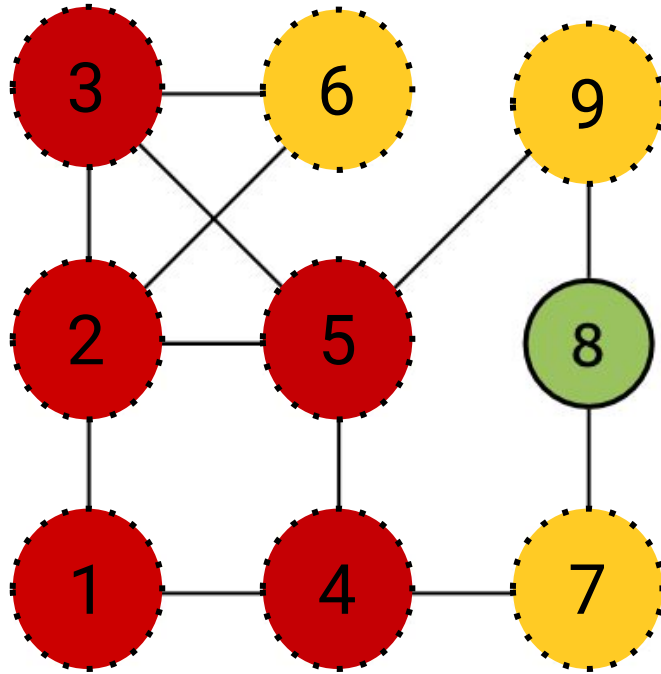
pending = [6, 7, 9]

Example



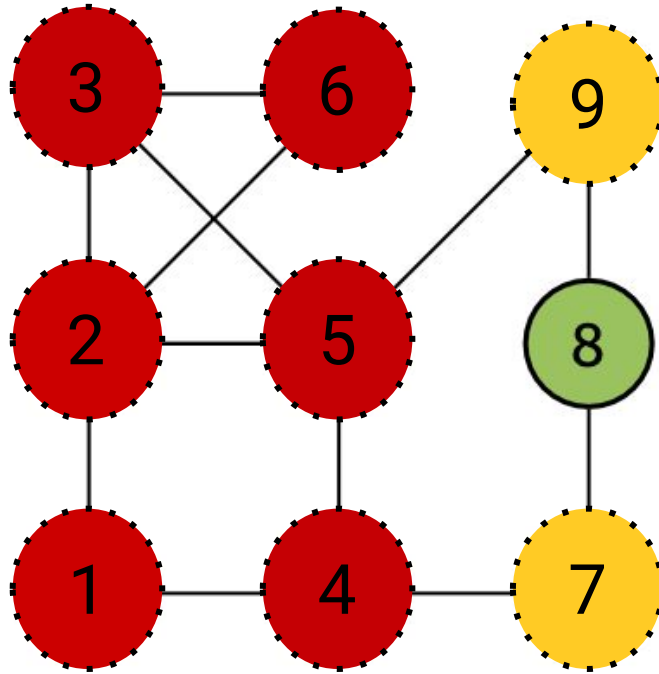
pending = [6, 7, 9, ?]

Example



pending = [6, 7, 9]

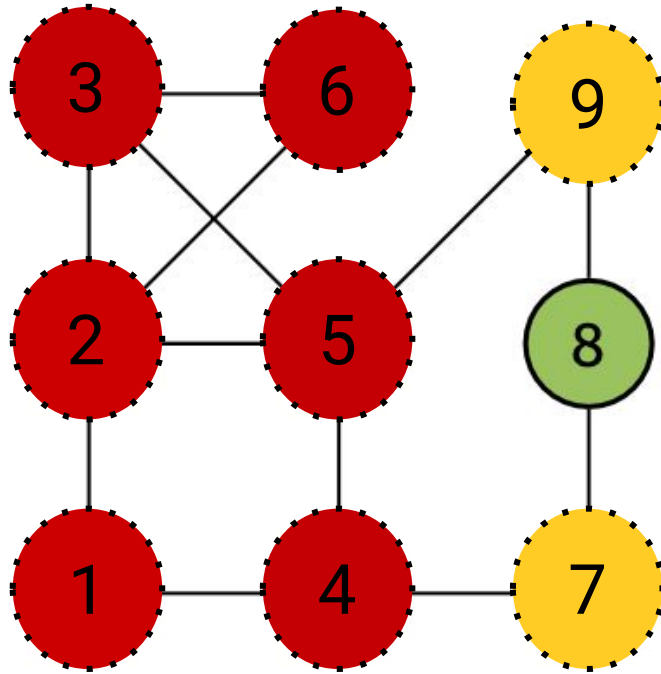
Example



After 6th iteration

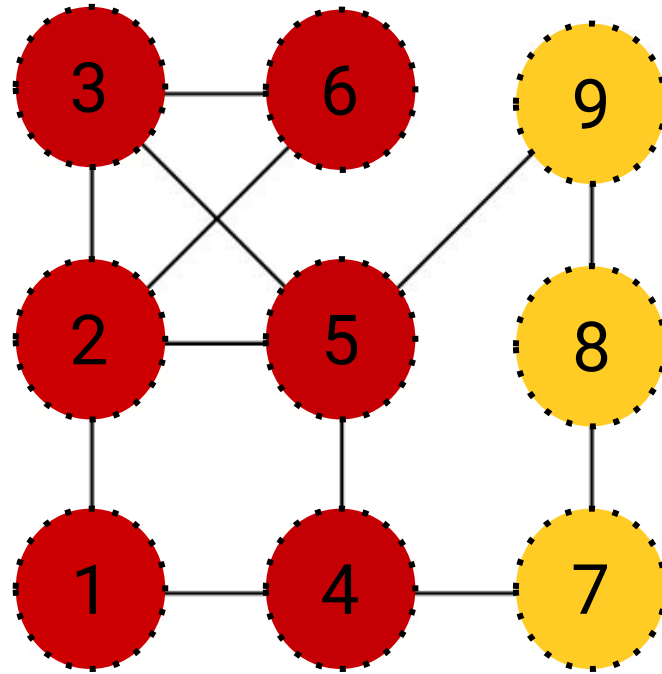
pending = [7, 9]

Example



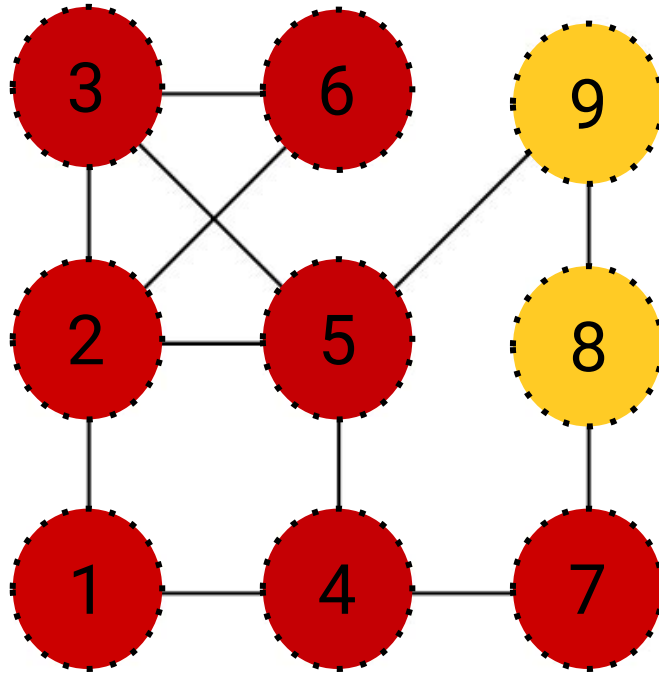
pending = [7, 9, ?]

Example



pending = [7, 9, 8]

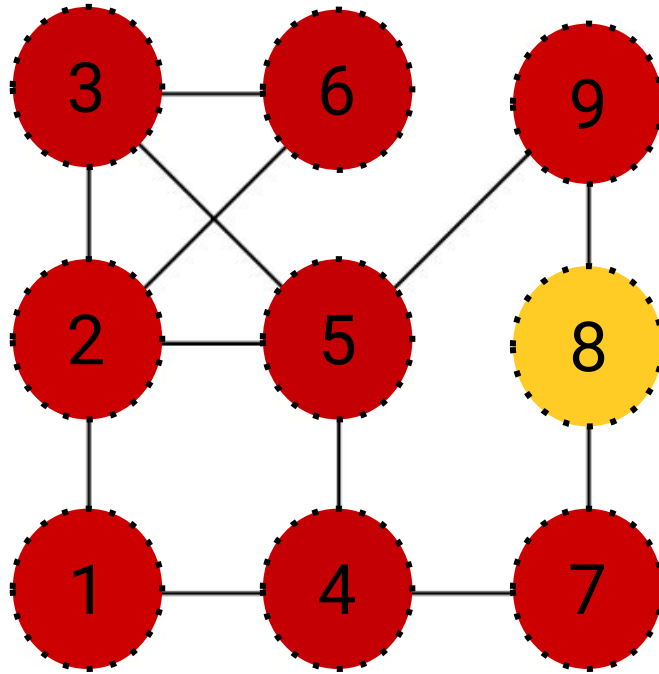
Example



After 7th iteration

pending = [9, 8]

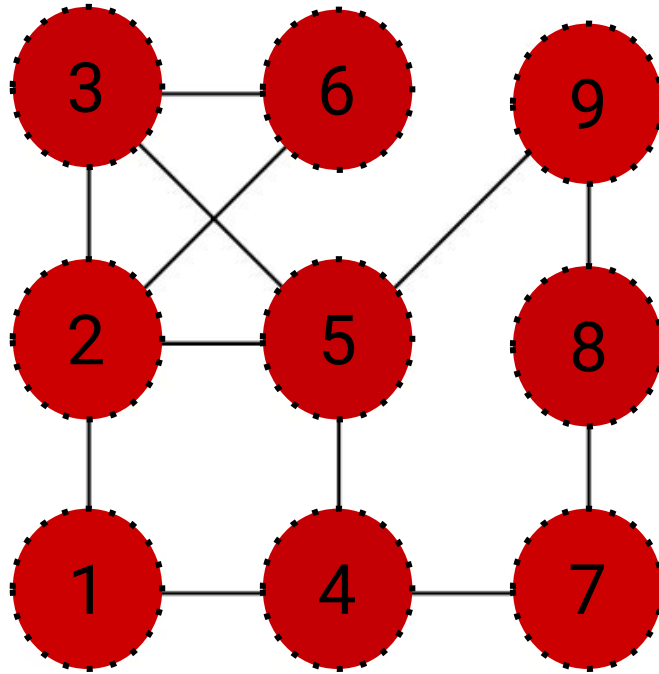
Example



pending = [8]

After 8th iteration

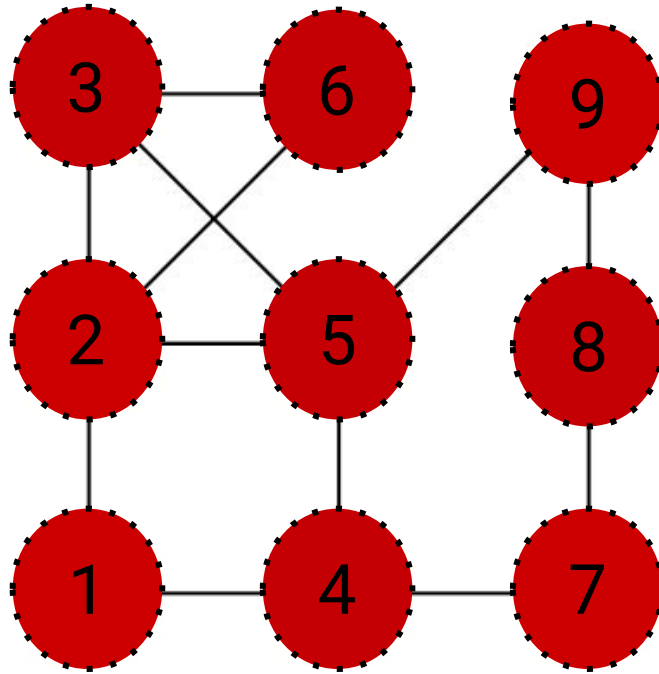
Example



pending = []

After 9th iteration

Example



After 9th iteration

pending = []

Did you recognize the data structure?

Implementation

- To store **pending** nodes, use a FIFO **queue**.
 - FIFO = "First in, first out".
- While queue is not empty:
 - Pop a node, u . (remove from the front)
 - Add **undiscovered** neighbors to queue. (to the back)

Queues in Python

- Want $\Theta(1)$ time pops/appends on either side.
- `from collections import deque` (“deck”).
 - `.popleft()` and `.pop()`
 - `list` doesn't have right time complexity!
 - `import queue` **isn't** what you want!
- Keep track of node status attribute using dictionary.

```
from collections import deque
```

```
def bfs(graph, source):
```

```
    """Start a BFS at `source`."""
```

```
    status = {node: 'undiscovered' for node in graph.nodes}
```

```
    status[source] = 'pending'
```

```
    pending = deque([source])
```

```
    # while there are still pending nodes
```

```
    while pending:
```

```
        # EXERCISE: fill this in...
```

```
from collections import deque
```

```
def bfs(graph, source):
```

```
    """Start a BFS at `source`."""
```

```
    status = {node: 'undiscovered' for node in graph.nodes}
```

```
    status[source] = 'pending'
```

```
    pending = deque([source])
```

```
    # while there are still pending nodes
```

```
    while pending:
```

```
        # EXERCISE: fill this in...
```

At every step:

- Visit **oldest pending** node.
- Mark its **undiscovered** neighbors as **pending**.

```
from collections import deque
```

```
def bfs(graph, source):
```

```
    """Start a BFS at `source`."""
```

```
    status = {node: 'undiscovered' for node in graph.nodes}
```

```
    status[source] = 'pending'
```

```
    pending = deque([source])
```

```
    # while there are still pending nodes
```

```
    while pending:
```

```
        u = pending.popleft() #remove the first elem
```

At every step:

- Visit **oldest pending** node.
- Mark its **undiscovered** neighbors as **pending**.

```
from collections import deque
```

```
def bfs(graph, source):
```

```
    """Start a BFS at `source`."""
```

```
    status = {node: 'undiscovered' for node in graph.nodes}
```

```
    status[source] = 'pending'
```

```
    pending = deque([source])
```

```
    # while there are still pending nodes
```

```
    while pending:
```

```
        u = pending.popleft() #remove the first elem
```

```
        for v in graph.neighbors(u):
```

At every step:

- Visit **oldest pending** node.
- Mark its **undiscovered** neighbors as **pending**.

```
from collections import deque
```

```
def bfs(graph, source):
```

```
    """Start a BFS at `source`."""
```

```
    status = {node: 'undiscovered' for node in graph.nodes}
```

```
    status[source] = 'pending'
```

```
    pending = deque([source])
```

```
    # while there are still pending nodes
```

```
    while pending:
```

```
        u = pending.popleft() #remove the first elem
```

```
        for v in graph.neighbors(u):
```

```
            if status[v] == 'undiscovered':
```

At every step:

- Visit **oldest pending** node.
- Mark its **undiscovered** neighbors as **pending**.

```
from collections import deque
```

```
def bfs(graph, source):
```

```
    """Start a BFS at `source`."""
```

```
    status = {node: 'undiscovered' for node in graph.nodes}
```

```
    status[source] = 'pending'
```

```
    pending = deque([source])
```

```
    # while there are still pending nodes
```

```
    while pending:
```

```
        u = pending.popleft() #remove the first elem
```

```
        for v in graph.neighbors(u):
```

```
            if status[v] == 'undiscovered':
```

```
                status[v] = 'pending'
```

At every step:

- Visit **oldest pending** node.
- Mark its **undiscovered** neighbors as **pending**.

```
from collections import deque
```

```
def bfs(graph, source):
```

```
    """Start a BFS at `source`."""
```

```
    status = {node: 'undiscovered' for node in graph.nodes}
```

```
    status[source] = 'pending'
```

```
    pending = deque([source])
```

```
    # while there are still pending nodes
```

```
    while pending:
```

```
        u = pending.popleft() #remove the first elem
```

```
        for v in graph.neighbors(u):
```

```
            if status[v] == 'undiscovered':
```

```
                status[v] = 'pending'
```

```
                pending.append(v)
```

At every step:

- Visit **oldest pending** node.
- Mark its **undiscovered** neighbors as **pending**.

```
from collections import deque
```

```
def bfs(graph, source):
```

```
    """Start a BFS at `source`."""
```

```
    status = {node: 'undiscovered' for node in graph.nodes}
```

```
    status[source] = 'pending'
```

```
    pending = deque([source])
```

```
    # while there are still pending nodes
```

```
    while pending:
```

```
        u = pending.popleft() #remove the first elem
```

```
        for v in graph.neighbors(u):
```

```
            if status[v] == 'undiscovered':
```

```
                status[v] = 'pending'
```

```
                pending.append(v)
```

```
        status[u] == 'visited'
```

At every step:

- Visit **oldest pending** node.
- Mark its **undiscovered** neighbors as **pending**.

BFS

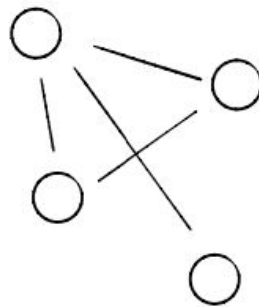
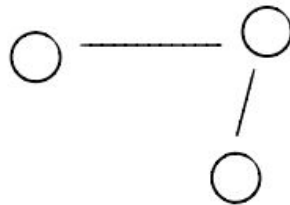
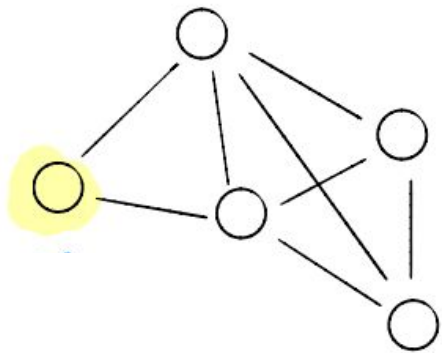
```
from collections import deque
def bfs(graph, source):
    """Start a BFS at `source`."""
    status = {node: 'undiscovered' for node in graph.nodes}
    status[source] = 'pending'
    pending = deque([source])
    # while there are still pending nodes
    while pending:
        u = pending.popleft()
        for v in graph.neighbors(u):
            # explore edge (u,v)
            if status[v] == 'undiscovered':
                status[v] = 'pending'
                # append to right
                pending.append(v)
        status[u] = 'visited'
```

Notes

- What does this code actually return?
- Nothing, yet. It is a **foundation**.
- BFS works just as well for directed graphs.

Analysis of BFS

Exercise: What will bfs do when run on a disconnected graph?



A: Discover all nodes

B: Inf. loop

C: Discover only some nodes.

Claim

- bfs with source u will visit all nodes **reachable** from u (*and only those nodes*).
- **Useful!**
 - Is there a path between u and v ?
 - Is graph connected?

Exploring with BFS

- BFS will visit all nodes **reachable** from source.
- If **disconnected**, BFS will **not visit** all nodes.
- We can do so with a **full BFS**.
 - **Idea**: “re-start” BFS on undiscovered node.
 - Must pass *statuses* between calls.

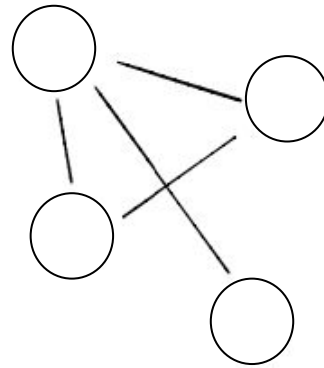
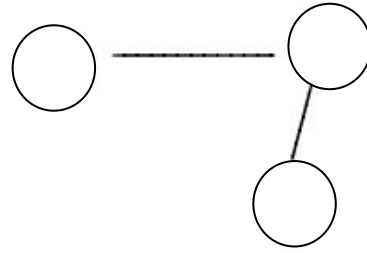
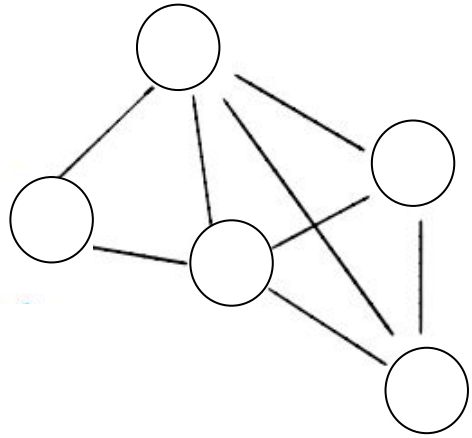
Making Full BFS: Modify bfs to accept statuses

```
def bfs(graph, source, status=None):  
    """Start a BFS at `source`."""  
    if status is None:  
        status = {node: 'undiscovered' for node in graph.nodes}  
    # ...
```

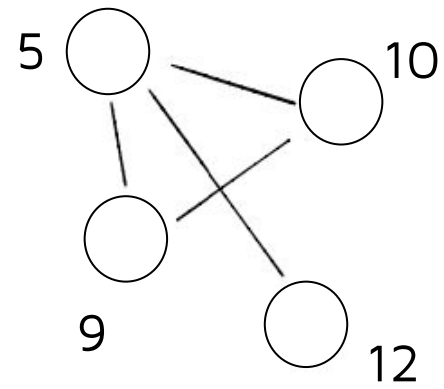
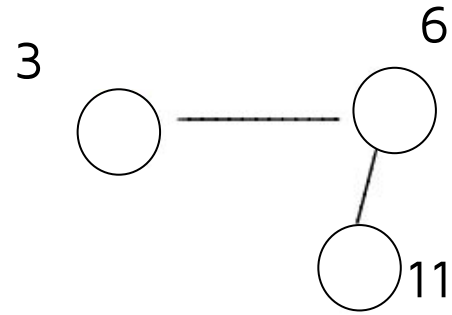
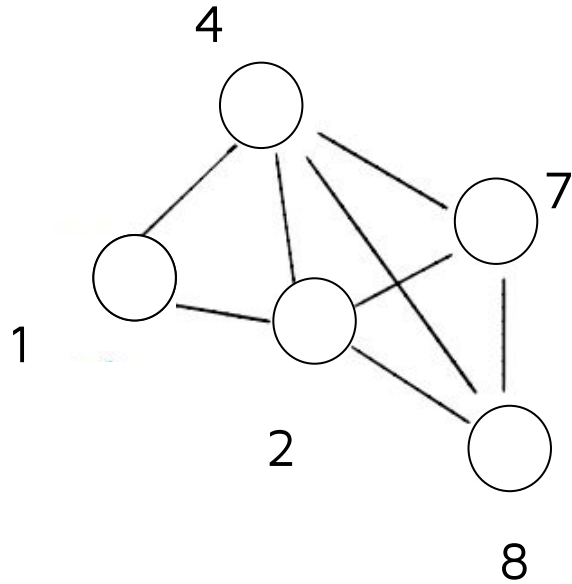
Making Full BFS: Call bfs multiple times

```
def full_bfs(graph):  
    status = {node: 'undiscovered' for node in graph.nodes}  
    for node in graph.nodes:  
        if status[node] == 'undiscovered':  
            bfs(graph, node, status)
```

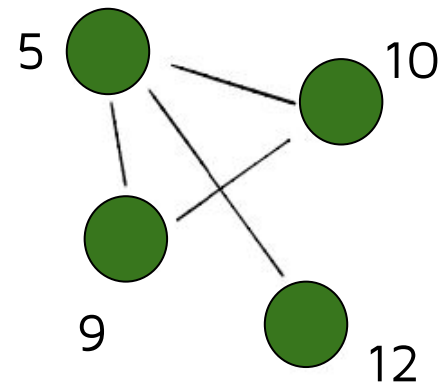
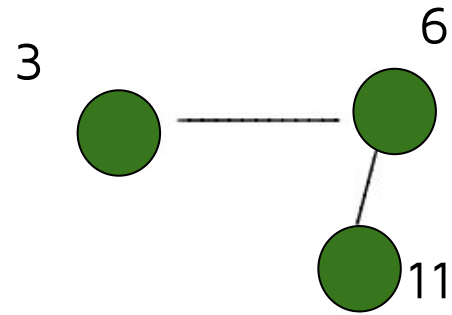
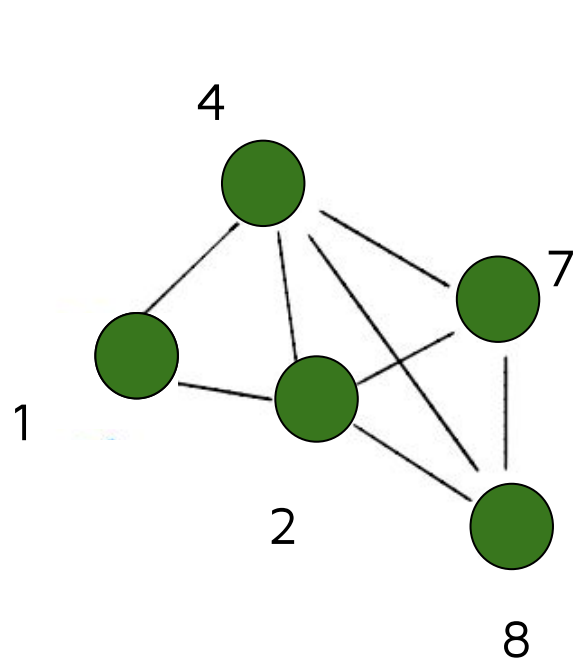
Example



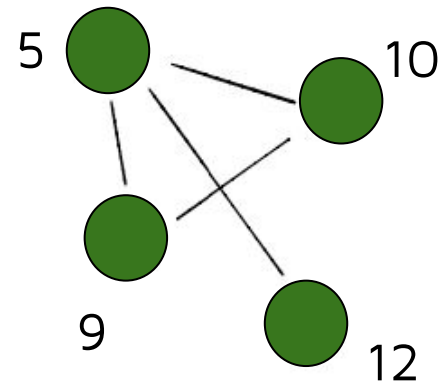
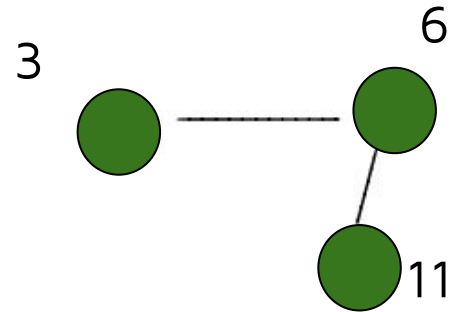
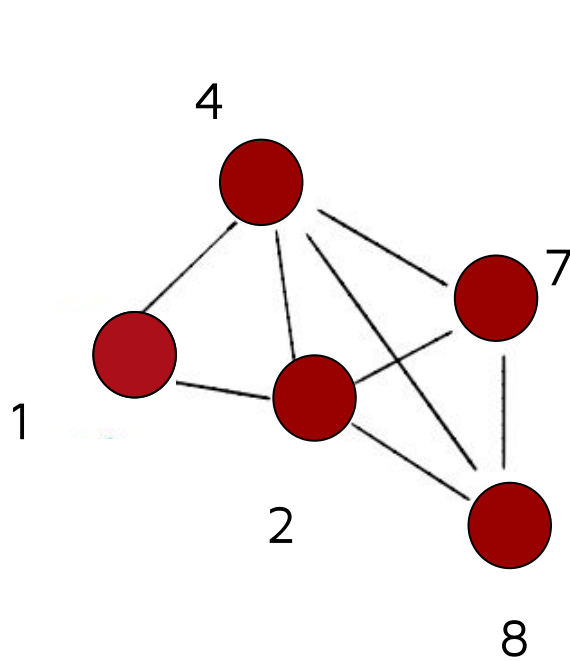
Example



Example

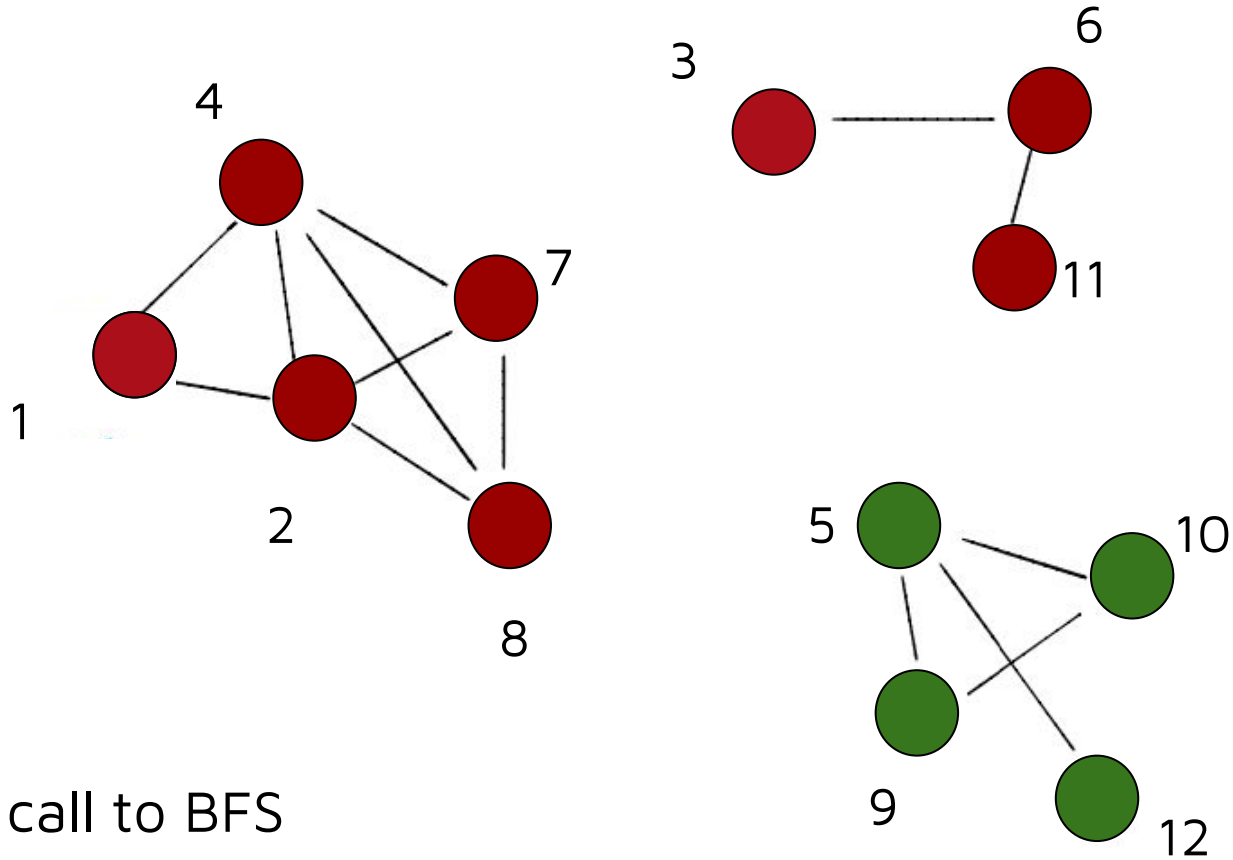


```
def full_bfs(graph):  
    status = {node: 'undiscovered' for node in graph.nodes}  
    for node in graph.nodes:  
        if status[node] == 'undiscovered'
```



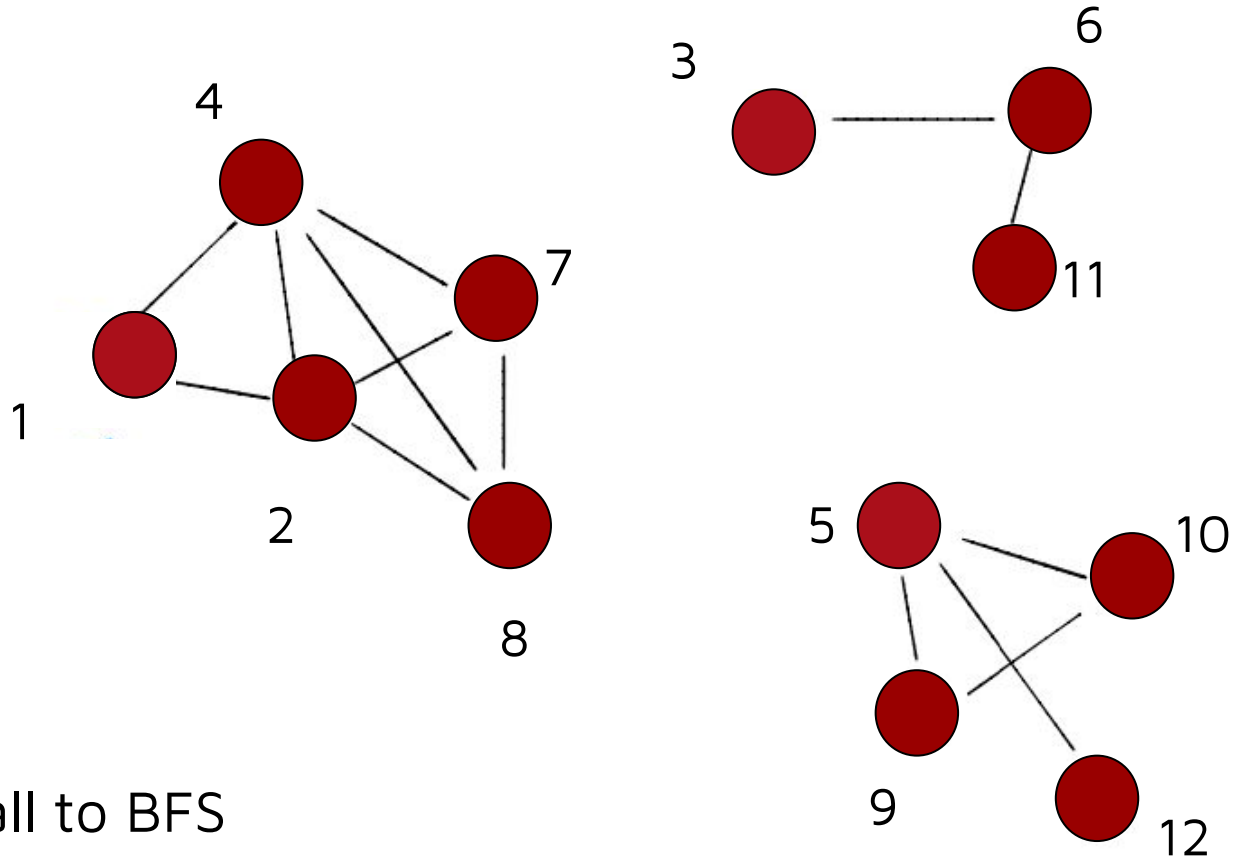
First call to BFS

```
def full_bfs(graph):  
    status = {node: 'undiscovered' for node in graph.nodes}  
    for node in graph.nodes:  
        if status[node] == 'undiscovered'
```



Second call to BFS

```
def full_bfs(graph):  
    status = {node: 'undiscovered' for node in graph.nodes}  
    for node in graph.nodes:  
        if status[node] == 'undiscovered'
```



Third call to BFS

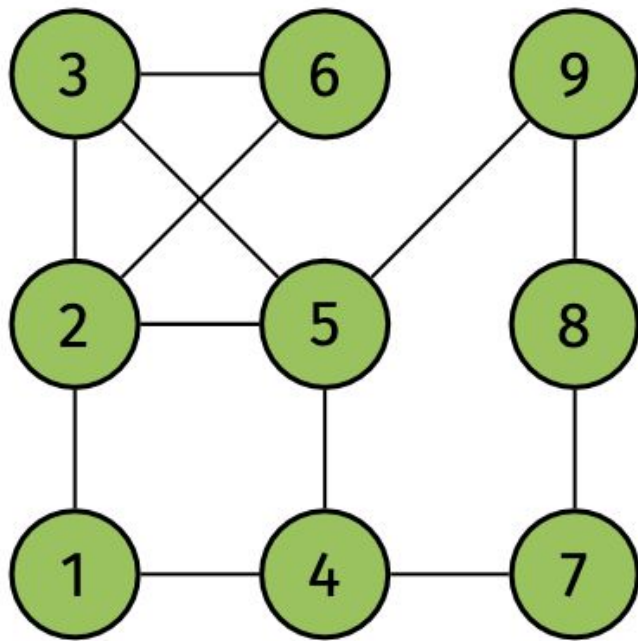
Observation

If there are k connected components, bfs in line 5 is called exactly k times

```
1  def full_bfs(graph):
2      status = {node: 'undiscovered' for node in graph.nodes}
3      for node in graph.nodes:
4          if status[node] == 'undiscovered':
5              bfs(graph, node, status)
```


Exercise

How many times is each node added to the queue in a BFS of the graph below?



A: Once

B: Twice

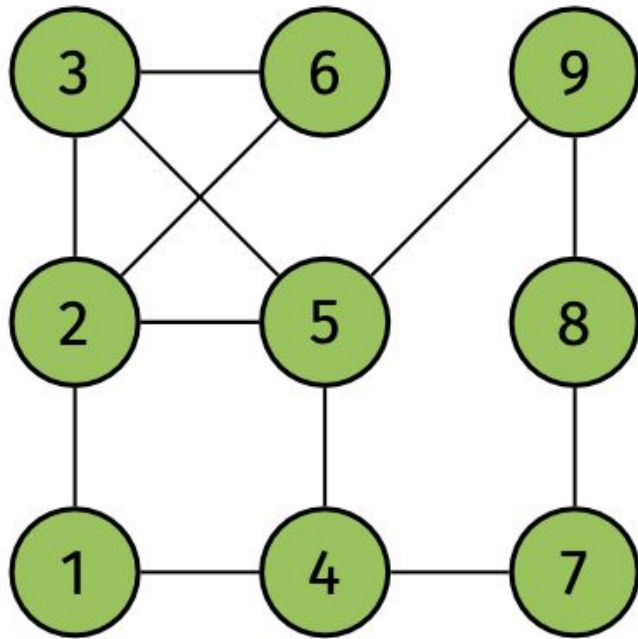
C: E times

D: V times

E: V + E times

Exercise

How many times is each edge “explored” in a BFS of the graph below?



A: Once

B: Twice

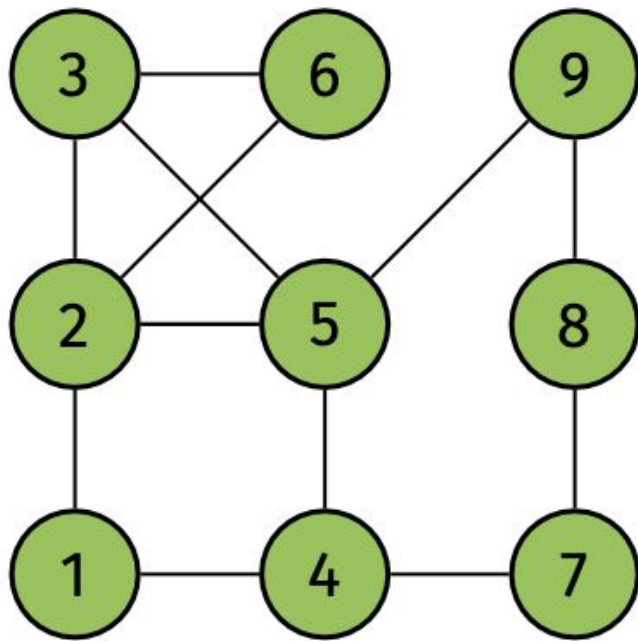
C: E times

D: V times

E: V + E times

Exercise

How many times is each edge “explored” in a BFS of the graph below?



A: Once

B: Twice

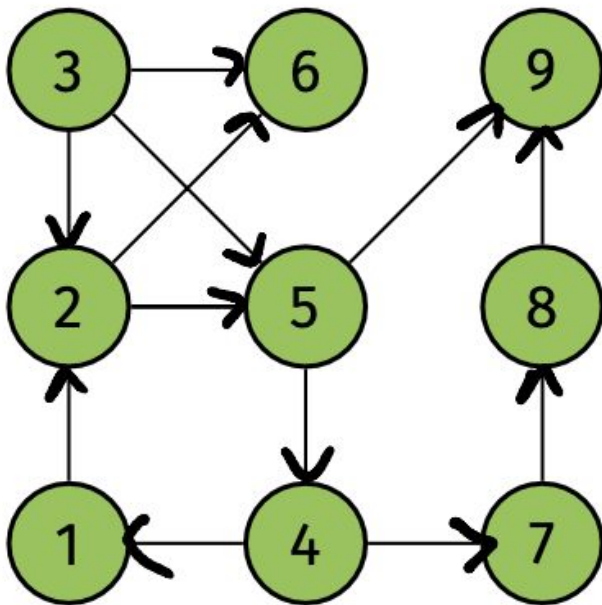
C: E times

D: V times

E: V + E times

Exercise

How many times is each edge “explored” in a BFS of the **directed** graph below?



A: Once

B: Twice

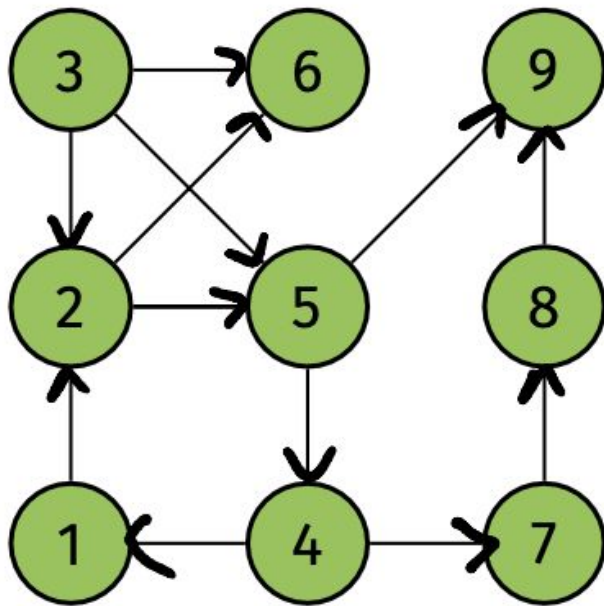
C: E times

D: V times

E: V + E times

Exercise

How many times is each edge “explored” in a BFS of the **directed** graph below?



A: Once

B: Twice

C: E times

D: V times

E: V + E times

Key Properties of full_bfs

- Each node added to queue **exactly once**.
- Each edge is *explored exactly*:
 - **once** if graph is **directed**.
 - **twice** if graph is **undirected**.

Time Complexity of full_bfs

- Analyzing full_bfs is easier than analyzing bfs.
 - full_bfs visits all nodes, no matter the graph.
- Result will be **upper bound** on time complexity of bfs.
- We'll use an **aggregate analysis**.

```
from collections import deque
```

```
def bfs(graph, source):
```

```
    """Start a BFS at `source`."""
```

```
    status = {node: 'undiscovered' for node in graph.nodes}
```

```
    status[source] = 'pending'
```

```
    pending = deque([source])
```

```
    # while there are still pending nodes
```

```
    while pending:
```

```
        u = pending.popleft()
```

```
        for v in graph.neighbors(u):
```

```
            # explore edge (u,v)
```

```
            if status[v] == 'undiscovered':
```

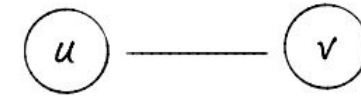
```
                status[v] = 'pending'
```

```
                # append to right
```

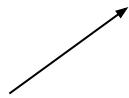
```
                pending.append(v)
```

```
        status[u] = 'visited'
```

$\Theta(V)$

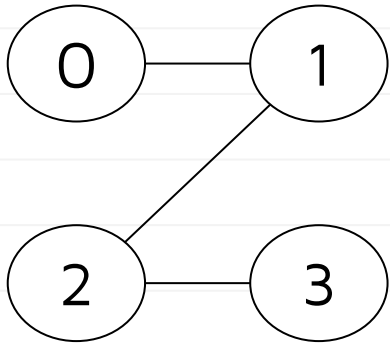


$\Theta(E)$



$\Theta(V + E)$

Exercise 4: Complexity



```
adj = [
  [1],
  [0, 2],
  [1, 3],
  [2]
]
```

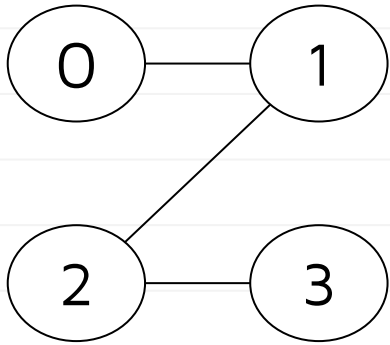
```
for u in range(len(adj)):
    for v in adj[u]:
        print(f"({u}, {v})")
```

What is the time complexity in terms of $|V|$ and $|E|$?

A: $\Theta(|E| + |V|)$ C: $\Theta(|E|)$

B: $\Theta(|E| * |V|)$ D: $\Theta(|V|)$

Exercise 4: Complexity



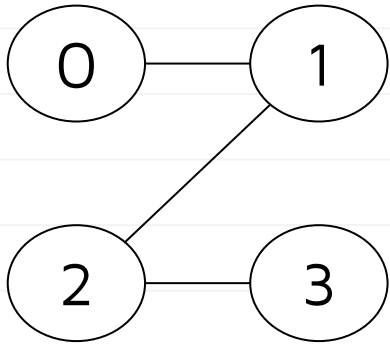
```
adj = [
  [1],
  [0, 2],
  [1, 3],
  [2]
]
```

```
for u in range(len(adj)):
    for v in adj[u]:
        print(f"({u}, {v})")
```

u is 0

v=1

Exercise 4: Complexity



```
adj = [
  [1],
  [0, 2],
  [1, 3],
  [2]
]
```

```
for u in range(len(adj)):
    for v in adj[u]:
        print(f"({u}, {v})")
```

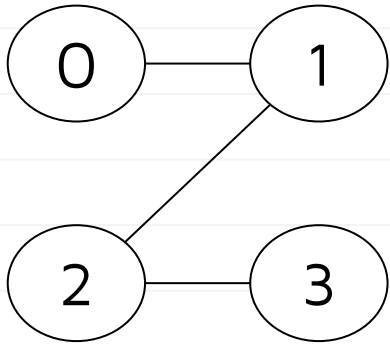
u is 0

u is 1

v=1

v=0, 2

Exercise 4: Complexity



```
adj = [
  [1],
  [0, 2],
  [1, 3],
  [2]
]
```

```
for u in range(len(adj)):
    for v in adj[u]:
        print(f"({u}, {v})")
```

u is 0

u is 1

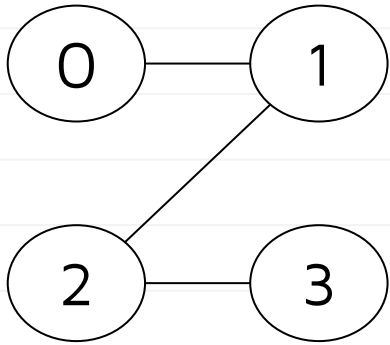
u is 2

v=1

v=0, 2

v=1, 3

Exercise 4: Complexity



```
adj = [
  [1],
  [0, 2],
  [1, 3],
  [2]
]
```

```
for u in range(len(adj)):
    for v in adj[u]:
        print(f"({u}, {v})")
```

u is 0

u is 1

u is 2

u is 3

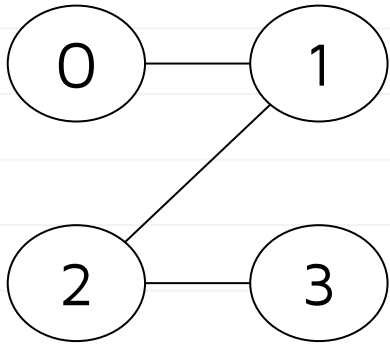
v=1

v=0, 2

v=1, 3

v = 2

Exercise 4: Complexity



```
adj = [
  [1],
  [0, 2],
  [1, 3],
  [2]
]
```

```
for u in range(len(adj)):
    for v in adj[u]:
        print(f"({u}, {v})")
```

u is 0

u is 1

u is 2

u is 3

v=1

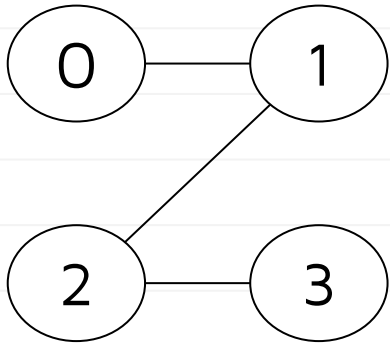
v=0, 2

v=1, 3

v = 2

Total of 6 iterations

Exercise 4: Complexity



```
adj = [
  [1],
  [0, 2],
  [1, 3],
  [2]
]
```

```
for u in range(len(adj)):
    for v in adj[u]:
        print(f"({u}, {v})")
```

u is 0

u is 1

u is 2

u is 3

v=1

v=0, 2

v=1, 3

v = 2

Total of 6 iterations (E)

Exercise 5:

```
adj = [  
    [],  
    [],  
    [],  
    []  
]
```

```
for u in range(len(adj)):  
    for v in adj[u]:  
        print(f"({u}, {v})")
```

0

1

2

3

u is 0

u is 1

u is 2

u is 3

1

1

1

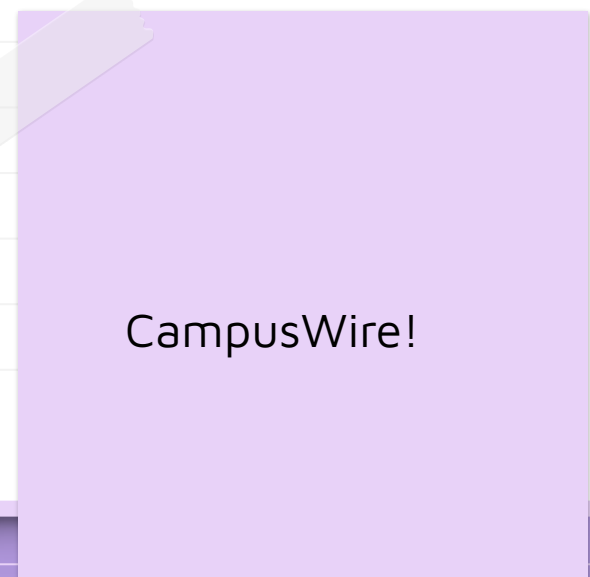
1

Total of 4 iterations (V)



Thank you!

Do you have any questions?



CampusWire!