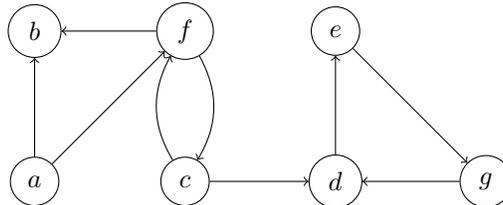

DSC 40B - Discussion 07

Problem 1.

Consider a *breadth*-first search on the graph shown in the figure, starting with node *c*.



- a) Suppose you call `bfs_shortest_paths(graph, 'c')` on the graph above. This function returns dictionaries `distance` and `predecessor`. Write down the contents of these dictionaries as they are when the function exits.

```
def bfs_shortest_paths(graph, source):
    status = {node: 'undiscovered' for node in graph.nodes}
    distance = {node: float('inf') for node in graph.nodes}
    predecessor = {node: None for node in graph.nodes}
    status[source] = 'pending'
    distance[source] = 0
    pending = deque([source])
    # while there are still pending nodes
    while pending:
        u = pending.popleft()
        for v in graph.neighbors(u):
            # explore edge (u,v)
            if status[v] == 'undiscovered':
                status[v] = 'pending'
                distance[v] = distance[u] + 1
                predecessor[v] = u
                # append to right
                pending.append(v)
        status[u] = 'visited'
    return predecessor, distance
```

Solution:

```
distance: {
  'a': ∞,
  'b': 2,
  'c': 0,
  'd': 1,
  'e': 2,
  'f': 1,
  'g': 3
}
predecessor: {
  'a': None,
```

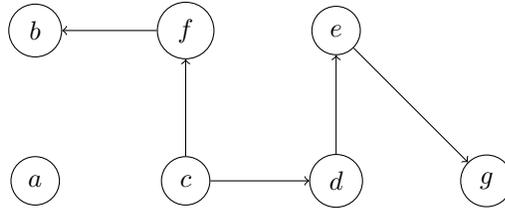
```

'b':f,
'c':None,
'd':c,
'e':d,
'f':c,
'g':e
}

```

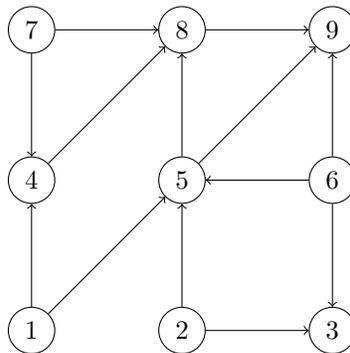
b) Mark the BFS trees produced on executing BFS on this graph.

Solution:



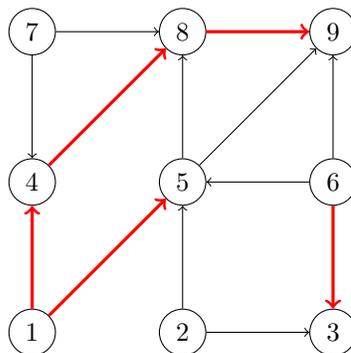
Problem 2.

Consider the following directed graph.



a) Make a bold arrow from node u to node v if u is the predecessor of node v in DFS. Use the convention that a node's neighbors are processed in ascending order by label.

Solution:



b) Fill in the table below so that it contains the start and finish times of each node after a DFS is performed on the above graph using node 1 as the source. Begin your start times with 1.

Node	Start	Finish
1	1	10
2	17	18
3	14	15
4	2	7
5	8	9
6	13	16
7	11	12
8	3	6
9	4	5

c) Topologically sort the vertices of the graph.

Solution: 2,6,3,7,1,5,4,8,9

Problem 3.

State whether the following statements are true or false.

a) Breadth first search on a directed graph always produces same number of BFS trees irrespective of order in which vertices are given and the neighbouring nodes are visited.

Solution: False.

b) Breadth first search on an undirected graph always produces same number of BFS trees irrespective of order in which vertices are given and the neighbouring nodes are visited.

Solution: True.

c) Both BFS and DFS require atleast $\Omega(V)$ memory.

Solution: True.

d) Consider a graph G on which BFS is run with node s as the source. Assume that BFS visits a node u in the graph before node v. Then $d(s, u) < d(s, v)$

Solution: False. $d(s, u) \leq d(s, v)$

e) Every directed acyclic graph has exactly one topological ordering.

Solution: False. There can be multiple topological orderings depending on the order of nodes chosen during DFS.

Problem 4.

Given an undirected graph $G=(V,E)$, give an algorithm to find if the graph is disconnected.

Solution: Run BFS or DFS on a node in G (since G is undirected, any node will do). If the size of the set of visited nodes does not equal $|V|$, then the graph is disconnected.

Figure 1: "Full" DFS

```
from data classes import dataclass
@dataclass
class Times:
    clock: int
    start: dict
    finish: dict

def full_dfs_times(graph):
    status = {node: 'undiscovered' for node in graph.nodes}
    predecessor = {node: None for node in graph.nodes}
    times=Times(clock=0, start={}, finish={})
    for u in graph.nodes:
        if status[u]=='undiscovered':
            dfs_times(graph, u, status, times)
    return times, predecessor

def dfs_times(graph, u, status, predecessor, times):
    times.clock+=1
    times.start[u]=times.clock
    status[u]='pending'
    for v in graph.neighbors(u):
        # explore edge (u, v)
        if status[v]=='undiscovered':
            predecessor[v]= u
            dfs_times(graph, v, status, times)
    status[u]='visited'
    times.clock+=1
    times.finish[u]=times.clock
```