## DSC 40B Theoretical Foundations II

Lecture 13 | Part 1

**Depth First Search** 

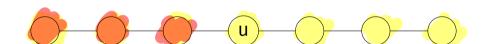
## **Visiting the Next Node**

- Which node do we process next in a search?
- BFS: the **oldest** pending node.
- DFS (today): the newest pending node.
  - Naturally recursive.
  - Useful for solving different problems.

## Example (BFS)



## **Example (DFS)**



```
def dfs(graph, u, status=None):
    """Start a DFS at `u`."""
    # initialize status if it was not passed
    if status is None:
        status = {node: 'undiscovered' for node in graph.nodes}

status[u] = 'pending'
for v in graph.neighbors(u): # explore edge (u, v)
```

if status[v] == 'undiscovered':
 dfs(graph, v, status)

status[u] = 'visited'

#### **Exercise**

Write the nested function calls for a DFS on the graph below.

```
def dfs(graph, u, status=None):
    """Start a DFS at `u`."""
    status[u] = 'pending'
    for v in graph.neighbors(u): # explore edge (u, v)
        if status[v] == 'undiscovered':
            dfs(graph, v, status)
    status[u] = 'visited'
```

dis(a)

#### **Differences**

- ▶ In **BFS**, we "finish" a node *u* before moving on to the next.
- ▶ In **DFS**, we go to many other nodes, but "come back" to u.

#### Main Idea

We'll see that the nested structure of the **recursive function calls** gives us useful new information about the graph's structure.

#### **Full DFS**

- ightharpoonup dfs(u) will visit all nodes **reachable** from u.
  - But not all nodes may be reachable from u!
- To visit all nodes in graph, need full DFS.

```
def full dfs(graph):
    status = {node: 'undiscovered' for node in graph.nodes}
    for node in graph.nodes:
        if status[node] == 'undiscovered'
            dfs(graph. node. status)
def dfs(graph, u, status=None):
    """Start a DES at `u`."""
    # initialize status if it was not passed
    if status is None:
        status = {node: 'undiscovered' for node in graph.nodes}
    status[u] = 'pending'
    for v in graph.neighbors(u): # explore edge (u, v)
        if status[v] == 'undiscovered':
            dfs(graph, v, status)
    status[u] = 'visited'
```

## **Time Complexity**

- In a full DFS:
  - dfs called on each node exactly once.
  - Like BFS, each edge is explored exactly:
    - once if directed
    - twice if undirected

► Time:  $\Theta(V + E)$ , just like BFS.

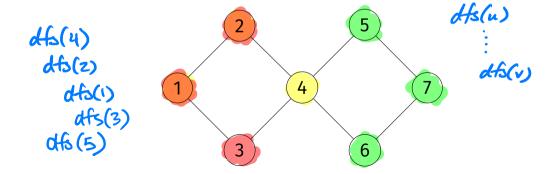
# DSC 40B Theoretical Foundation II

Lecture 13 | Part 2

**Nesting Properties of DFS** 

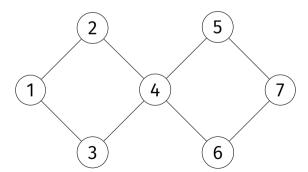
#### **Exercise**

**True** or **False**: if v is reachable from u and v is undiscovered when dfs(u) is called, then dfs(v) must be called during dfs(u).



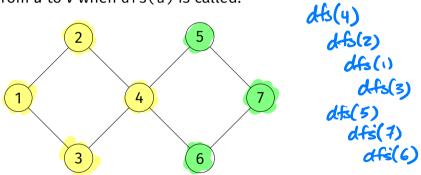
#### False!

- Suppose dfs(4) is the root call.
  - ▶ When dfs(1) is called, node 5 is undiscovered.
  - ▶ But dfs(5) is **not** called during dfs(1).



#### However...

This intuition is correct if there is a path of **undiscovered** nodes from *u* to *v* when dfs(u) is called.



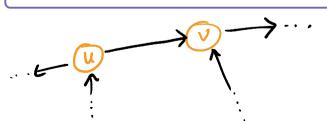
## **Key Property of DFS (Informal)**

- If at the time dfs(u) is called...
  - 1. v is undiscovered; and
  - 2. there is a path of **undiscovered** nodes from *u* to *v*,
- ...then dfs(v) will start and finish during the call to dfs(u).

#### **Exercise**

Suppose while visiting node u, we see that neighbor v is **pending**. True or False: there is a path from v to u.





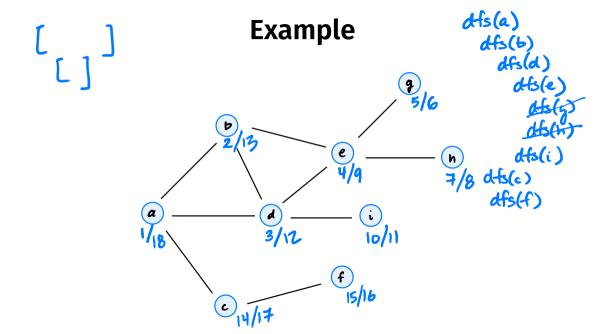
#### **Start and Finish Times**

- Keep a running clock (an integer).
- ► For each node, record
  ► Start time: time when marked pending
  - Finish time: time when marked visited

Increment clock whenever node is marked pending/visited

```
adataclass
class Times.
    clock: int
    start · dict
    finish: dict
def full dfs times(graph):
    status = {node: 'undiscovered' for node in graph.nodes}
    predecessor = {node: None for node in graph.nodes}
    times = Times(clock=0, start={}, finish={})
    for u in graph.nodes:
        if status[u] == 'undiscovered':
            dfs times(graph. u. status. times)
    return times, predecessor
def dfs times(graph, u. status, predecessor, times):
    times clock += 1
    times.start[u] = times.clock
    status[u] = 'pending'
    for v in graph.neighbors(u): # explore edge (u, v)
        if status[v] == 'undiscovered':
            predecessor[v] = u
            dfs times(graph, v, status, times)
    status[u] = 'visited'
    times.clock += 1
    times.finish[u] = times.clock
```

from dataclasses import dataclass



#### **Key Property of DFS**

- Suppose dfs(u) is called before dfs(v).
- If when dfs(u) is called there is a path of undiscovered nodes from u to v, then: start[u] < start[v] < finish[v] < finish[u].</p>
- Otherwise: start[u] < finish[u] < start[v] < finish[v].</p>

#### **Key Property**

- ► Take any two nodes u and v ( $u \neq v$ ).
- Assume for simplicity that start[u] < start[v].</p>
- Exactly one of these is true:
  - start[u] < start[v] < finish[v] < finish[u]</pre>
  - start[u] < finish[u] < start[v] < finish[v]</pre>

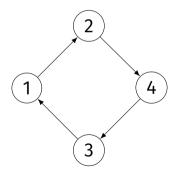
# DSC 40B Theoretical Foundations II

Lecture 13 | Part 3

**Cycles** 

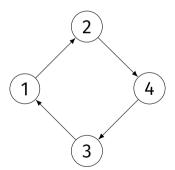
## Cycle

A cycle in a directed graph is a path that starts and ends at the same node.



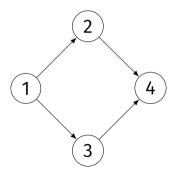
## Cycle

Alternatively: there is a cycle if u is reachable from v and v is reachable from u, for some  $u \neq v$ .



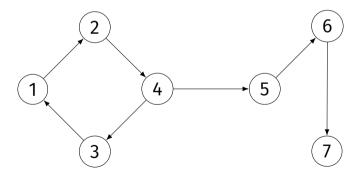
#### **DAG**

► A directed acyclic graph (DAG) is a directed graph with **no cycles**.



## **Cyclic Graphs**

- A graph is cyclic even if it has only one cycle.
  - It doesn't have to be the whole graph.



### **Detecting Cycles**

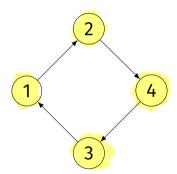


We check for cycles by looking for back edges in a full DFS.

(u, v) is a back edge if while visiting node u, we see that v is pending.

```
for v in graph.neighbors(u): # explore edge (u, v)
   if status[v] == 'undiscovered':
        dfs(graph, v, status)
   elif status[v] == 'pending':
        # back edge (u, v) found!
```

## **Example**



A directed graph has a cycle **if (and only if)** a full DFS

**Theorem** 

finds a back edge.

## Why?

- If a back edge (u, v) is found, then a cycle exists.
  - ightharpoonup Suppose v is pending when we visit u.
  - This means that there is a path from v to u.
  - There is also a path from *u* to *v*.
  - So there is a cycle.

## Why?

- ▶ If a cycle exists, then there is a back edge.
  - ▶ Suppose there is a cycle  $v_1 \rightarrow v_2 \rightarrow \cdots \rightarrow v_k \rightarrow v_1$ .
  - Without loss of generality, assume  $v_1$  is the first node in the cycle that is visited by the full DFS.
  - At the moment of dfs( $v_1$ ), there is a path of undiscovered nodes between  $v_1$  and  $v_k$ .
  - ► Therefore  $dfs(v_k)$  will be called during  $dfs(v_1)$ .
  - During dfs(v\_k), we'll see the back edge.

#### **Exercise**

Suppose v is reachable from u in a DAG.

True or false: after a full DFS, finish[v] < finish[u].

### Claim

finish[v] < finish[u]</pre>

▶ If *v* is reachable from *u* in a DAG, then:

## DSC 40B Theoretical Foundations II

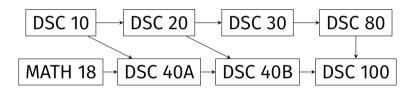
Lecture 13 | Part 4

**Topological Sort** 

## **Applications of DFS**

- ► Is node v reachable from node u? **DFS**, **BFS**
- Is the graph connected? DFS, BFS
- How many connected components? DFS, BFS
- Find the shortest path between u and v. DFS, BFS
- Does the graph have a cycle? DFS, BFS

## **Prerequisite Graphs**



**Goal:** find order in which classes should be taken in order to satisfy the prerequisites of DSC 100.

#### **Note**

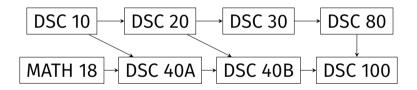
Prerequisite graphs are<sup>1</sup> DAGs.

<sup>&</sup>lt;sup>1</sup>Or they should be, at least!

#### **Topological Sorts**

- **► Given**: a DAG, *G* = (*V*, *E*).
- ► Compute: an ordering of V such that if  $(u, v) \in E$ , then u comes before v in the ordering
- ► This is called a **topological sort** of *G*.

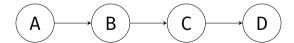
#### **Example**



MATH 18, DSC 10, DSC 40A, DSC 20, DSC 40B, DSC 30, DSC 80, DSC 100

## **Computing a Topological Sort**

- How do we compute a topological sort, algorithmically?
- Observation: if v is reachable from u, v must come after u in the topological sort.



#### Recall

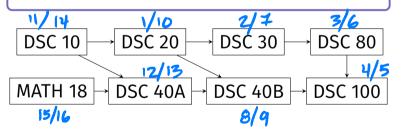
- ► Take any two nodes u and v ( $u \neq v$ ).
- Assume the graph is a DAG, run DFS.
- ▶ If v is reachable from u, then finish[v] < finish[u].</p>

#### **Putting it together...**

- ► **Observation:** If *v* is reachable from *u*, then *v* must come after *u* in the topological sort.
- **Recall:** If v is reachable from u, then finish[v] < finish[u].</p>

#### Exercise

Compute start and finish times using DSC 10 as the source.



#### Idea

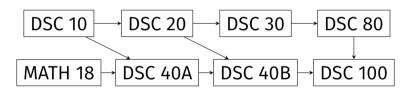
- ▶ **Observation:** If *v* is reachable from *u*, then *v* must come after *u* in the topological sort.
- ▶ Recall: If v is reachable from u, then finish[v] < finish[u].</p>
- ► **Therefore:** if finish[v] < finish[u], then v must come after u in the topological sort.
- Idea: sort nodes in descending order by finish time.

V,E

#### **Algorithm**

- To find a topological sort (if it exists):
  - Compute times with Full DFS.
  - Sort in descending order by finish time.
- ► Time complexity:

## **Example**



#### Note

There can be many valid topological sorts!

....