DSC 40B

Theoretical Foundations II

Lecture 13 | Part 1

Depth First Search

Visiting the Next Node

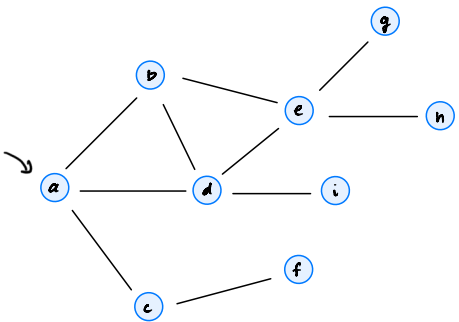
- Which node do we process next in a search?
- BFS: the **oldest** pending node.
- DFS (today): the **newest** pending node.
  - Naturally recursive.

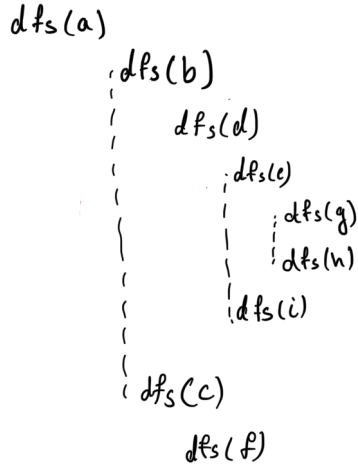
```
def dfs(graph, u, status=None):
    """Start a DFS at `u`."""
    # initialize status if it was not passed
    if status is None:
        status = {node: 'undiscovered' for node in graph.nodes}

    status[u] = 'pending'
    for v in graph.neighbors(u): # explore edge (u, v)
        if status[v] == 'undiscovered':
            dfs(graph, v, status)
    status[u] = 'visited'
```

Example

```
def dfs(graph, u, status=None):
    """Start a DFS at `u`."""
    ...
    status[u] = 'pending'
    for v in graph.neighbors(u): # explore edge (u, v)
        if status[v] == 'undiscovered':
            dfs(graph, v, status)
    status[u] = 'visited'
```





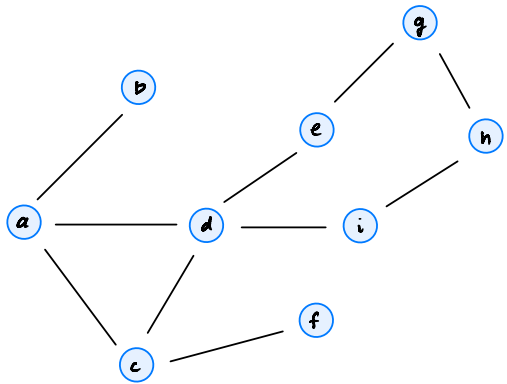
Main Idea

We'll see that the structure of the nested function calls gives us useful information about the graph's structure.

* In BFS, we finish a node u before moving on to the next.
* In DFS, we go to many other nodes, but "come back" to u.

Exercise

Write the nested function calls for a DFS on the graph below.



Full DFS

- DFS will visit all nodes reachable from source.
- To visit all nodes in graph, need **full DFS**.

```
def full_dfs(graph):
    status = {node: 'undiscovered' for node in graph.nodes}
    for node in graph.nodes:
        if status[node] == 'undiscovered'
            dfs(graph, node, status)
```

```python
def full_dfs(graph):
    status = {node: 'undiscovered' for node in graph.nodes}
    for node in graph.nodes:
        if status[node] == 'undiscovered'
            dfs(graph, node, status)


def dfs(graph, u, status=None):
    """Start a DFS at `u`."""
    # initialize status if it was not passed
    if status is None:
        status = {node: 'undiscovered' for node in graph.nodes}

    status[u] = 'pending'
    for v in graph.neighbors(u): # explore edge (u, v)
        if status[v] == 'undiscovered':
            dfs(graph, v, status)
    status[u] = 'visited'
```

Time Complexity

- In a full DFS:
  - `dfs` called on each node exactly once.
  - Like BFS, each edge is explored exactly:
    - once if directed
    - twice if undirected

- Time: $\Theta(V + E)$, just like BFS.

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Lecture 13 | Part 2

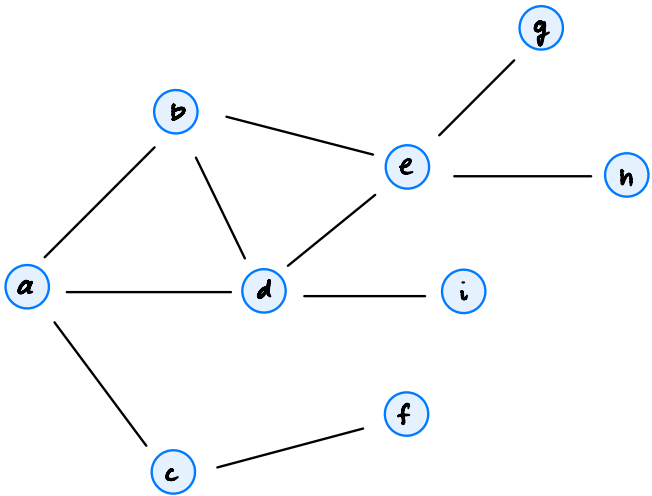
Nesting Properties of DFS

Key Property of DFS (Informal)

- Suppose *v* is reachable from *u*, and *v* is **undiscovered** at the time of `dfs(u)`.

- If there is a path of undiscovered nodes from *u* to *v* at the time of `dfs(u)`:
  - `dfs(v)` will be run.
  - `v` will be marked as **visited**.

Example



Start and Finish Times

- Keep a running clock (an integer).
- For each node, record
  - **Start time**: time when marked pending
  - **Finish time**: time when marked visited
- Increment clock whenever node is marked pending/visited

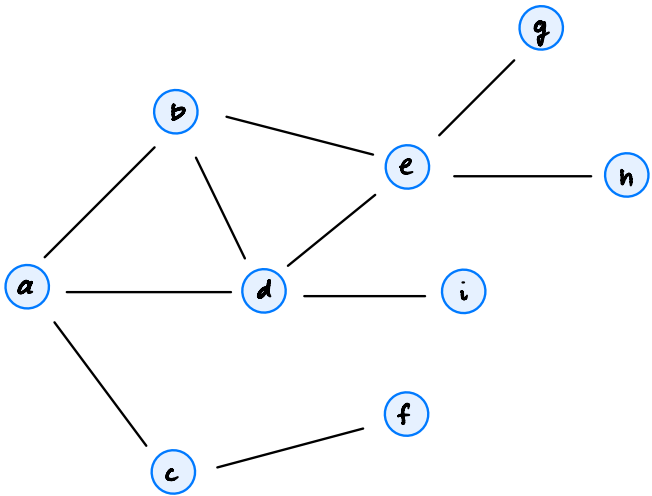
```python
from dataclasses import dataclass

@dataclass
class Times:
    clock: int
    start: dict
    finish: dict

def full_dfs_times(graph):
    status = {node: 'undiscovered' for node in graph.nodes}
    predecessor = {node: None for node in graph.nodes}
    times = Times(clock=0, start={}, finish={})
    for u in graph.nodes:
        if status[u] == 'undiscovered':
            dfs_times(graph, u, status, times)
    return times, predecessor

def dfs_times(graph, u, status, predecessor, times):
    times.clock += 1
    times.start[u] = times.clock
    status[u] = 'pending'
    for v in graph.neighbors(u): # explore edge (u, v)
        if status[v] == 'undiscovered':
            predecessor[v] = u
            dfs_times(graph, v, status, times)
    status[u] = 'visited'
    times.clock += 1
    times.finish[u] = times.clock
```

Example



Key Property

- Take any two nodes u and v ($u \neq v$).
- If v is *started* between `start[u]` and `finish[u]`, then v is *finished* between `start[u]` and `finish[u]`.

Key Property

- Take any two nodes u and v ($u \neq v$).
- Assume for simplicity that `start[u]` < `start[v]`.
- Exactly one of these is true:
  - `start[u]` < `start[v]` < `finish[v]` < `finish[u]`
  - `start[u]` < `finish[u]` < `start[v]` < `finish[v]`

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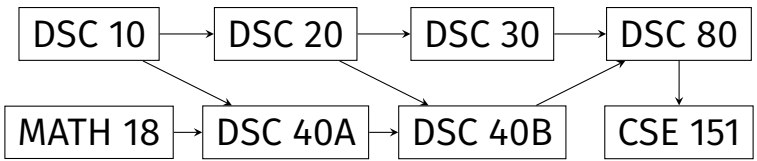
Lecture 13 | Part 3

Topological Sort

Applications of DFS

- Is node v reachable from node u?
- Is the graph connected?
- How many connected components?
- What is the shortest path between u and v? **No**.

Prerequisite Graphs



Goal: find order in which to take classes satisfying prerequisites.

Directed Acyclic Graphs

- A **directed cycle** is a path from a node to itself with at least one edge.
- A **directed acyclic graph (DAG)** is a directed graph with no directed cycles.

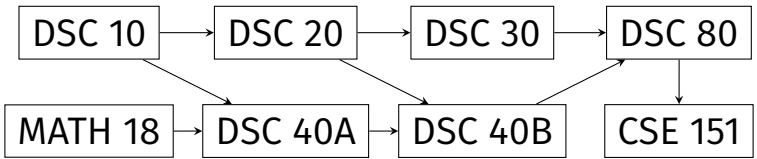
Example

- Prerequisite graphs are DAGs.
  - Or at least, they should be!

Topological Sorts

- **Given**: a DAG, $G = (V, E)$.
- **Compute**: an ordering of V such that if $(u, v) \in E$, then u comes before v in the ordering
- This is called a **topological sort** of G.

Example



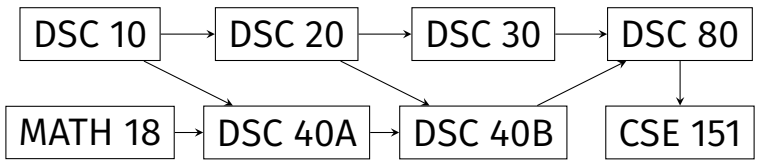
MATH 18, DSC 10, DSC 40A, DSC 20, DSC 40B, DSC 30, DSC 80, CSE 151

Key Property

- Take any two nodes u and v ($u \neq v$).
- Assume the graph is a DAG.
- **Example**: If v is reachable from u, then `finish[v]` < `finish[u]`.

Exercise

Compute start and finish times using DSC 10 as the source.



An Algorithm

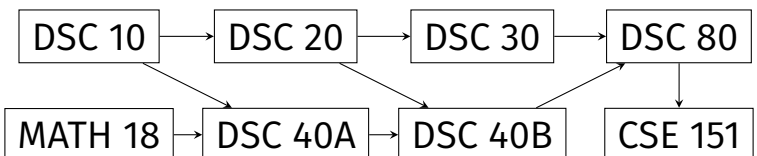
- **Recall**: If v is reachable from u, then `finish[v]` ≤ `finish[u]`.
- If v is reachable from u, u should come before v.
- Idea: nodes with later finish times should come first.

Algorithm

- To find a topological sort (if it exists):
  - Compute times with Full DFS.
  - Sort in **descending** order by finish time.

- Time complexity:

Example



Note

- There can be many valid topological sorts!