DSC 40B Theoretical Foundations II

Lecture 4 | Part 1

**The Movie Problem** 

## **The Movie Problem**



# **The Movie Problem**

- Given: an array movies of movie durations, and the flight duration t
- Find: two movies whose durations add to t.
   If no two movies sum to t, return None.

#### Exercise

Design a brute force solution to the problem. What is its time complexity?

# $1 n^2$

```
def find_movies(movies, t):
    n = len(movies)
    for i in range(n):
        for j in range(i + 1, n):
            if movies[i] + movies[j] == t:
                return (i, j)
    return None
```

# Time Complexity

- It looks like there is a **best** case and **worst** case.
- How do we formalize this?

## For the future...

- Can you come up with a better algorithm?
- What is the best possible time complexity?

DSC 40B Theoretical Foundations II

Lecture 4 | Part 2

**Best and Worst Cases** 

### Example 1: mean

O(n)

```
def mean(arr):
   total = 0
   for x in arr:
        total += x
   return total / len(arr)
```

# Time Complexity of mean

Linear time,  $\Theta(n)$ .

Depends only on the array's size, n, not on its actual elements.

## **Example 2: Linear Search**

**Given**: an array arr of numbers and a target t.

Find: the index of t in arr, or None if it is missing.

► Example: arr = [-3, -7, 2, 9, 1, 4](0,-3), (1,-4), (2,2), (3,4)  $t=9 \rightarrow 3$ 

```
def linear_search(arr, t):
    for i, x in enumerate(arr):
        if x == t:
            return i
        return None
```

#### **Exercise**

```
What is the time complexity of linear_search?
```

```
def linear_search(arr, t):
    for i, x in enumerate(arr):
        if x == t:
            return i
    return None
```

# Observation

It looks like there are two extreme cases...

### The **Best** Case

- When the target, t, is the very first element.
- ► The loop exits after one iteration.
- Θ(1) time?

### The Worst Case

- When the target, t, is not in the array at all.
- ► The loop exits after *n* iterations.
- Θ(n) time?

# **Time Complexity**

- linear\_search can take vastly different amounts of time on two inputs of the same size.
   Depends on actual elements as well as size.
- It has no single, overall time complexity.
- Instead we'll report best and worst case time complexities.

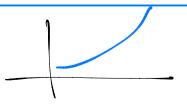
# **Best Case Time Complexity**

How does the time taken in the **best case** grow as the input gets larger?

#### Definition

Define  $T_{\text{best}}(n)$  to be the **least** time taken by the algorithm on any input of size *n*.

The asymptotic growth of  $T_{\text{best}}(n)$  is the algorithm's **best case asymptotic time complexity**.



def foo(n): if n < 1\_000\_000 : else: Best 10<sup>6</sup>

- In linear\_search's best case, T<sub>best</sub>(n) = c, no matter how large the array is.
- The **best case time complexity** is  $\Theta(1)$ .

# Worst Case Time Complexity

How does the time taken in the worst case grow as the input gets larger?

#### Definition

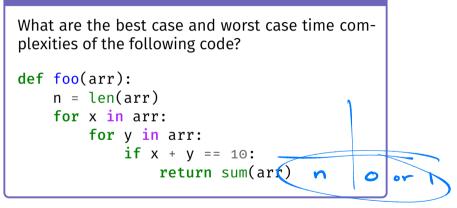
Define  $T_{worst}(n)$  to be the **most** time taken by the algorithm on any input of size n.

The asymptotic growth of  $T_{worst}(n)$  is the algorithm's worst case asymptotic time complexity.

### Worst Case

- In the worst case, linear\_search iterates through the entire array.
- The worst case time complexity is  $\Theta(n)$ .





$$T(n) = \dots n$$

### **Best Case**

- When the first element is 5, so x + y = 10.
- sum(arr) takes Θ(n) time.
- Exits, taking  $\Theta(n)$  time in total.

### **Worst Case**

- No two elements sum to 10.
- Has to loop over all  $\Theta(n^2)$  pairs.
- Worst case time complexity:  $\Theta(n^2)$ .
- Note: it's not Θ(n<sup>3</sup>), since the sum(arr) only runs once!

# **Caution!**

- The best case is never: "the input is of size one".
- The best case is about the structure of the input, not its size.
- Not always constant time! Example: sorting.

## Note

- An algorithm like linear\_search doesn't have one single time complexity.
- An algorithm like mean does, since the best and worst case time complexities coincide.

#### Main Idea

Reporting **best** and **worst** case time complexities gives us a richer of the performance of the algorithm.

DSC 40B Theoretical Foundations II

Lecture 4 | Part 3

**Average Case** 

# Time Taken, Typically

Best case and worst case can be misleading.
 Depend on a single good/bad input.

- How much time is taken, typically?
- Idea: compute the average time taken over all possible inputs.

## **Recall: The Expectation**

The expected value of a random variable X is:

$$\sum_{x} x \cdot P(X = x)$$

winningsprobabilityExpected winnings:\$050% $$0 \times (0.5) + $1 \times (0.3) + $10 \times (.16) + $50(.02)$ \$1030% $$0 \times (0.5) + $1 \times (0.3) + $10 \times (.16) + $50(.02)$ \$1018%= \$0 + \$0.30 + \$1.80 + \$1.20 + \$

### **Average Case**

We'll compute the expected time over all cases:

$$T_{avg}(n) = \sum_{case \in all \ cases} P(case) \cdot T(case)$$

Called the average case time complexity.

# Strategy for Finding Average Case

- **Step 0:** Make assumption about distribution of inputs.
- **Step 1:** Determine the possible cases.
- **Step 2:** Determine the probability of each case.
- **Step 3:** Determine the time taken for each case.
- **Step 4:** Compute the expected time (average).

# **Example: Linear Search**

```
Recall linear search:
```

```
def linear_search(arr, t):
    for i, x in enumerate(arr):
        if x == t:
            return i
        return None
```

```
Best case? Worst case?
```

# Example: Linear Search

What is the average case time complexity of linear search?

## **Step 0: Assume input distribution**

- We must assume something about the input.
- Example: Target must be in array, equally-likely to be any element, no duplicates.
- This is usually given to you.

### **Step 1: Determine the Cases**

Example: linear search.

Case 1: target is first element Case 2: target is second element : Case n: target is nth element Case n + 1: target is not in array

## **Step 2: Case Probabilities**

What is the probability that we see each case?
 Example: what is the probability that the target is the *k*th element?

This is where we use assumptions from Step 0.

# Example

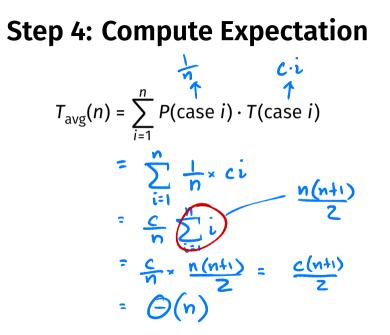
- Assume: target is in the array exactly once, equally-likely to be any element.
- Each case has probability 1/*n*.

$$P(Case \propto) = \frac{1}{n}$$

# Step 3: Case Times

- Determine time taken in each case.
- Example: linear search.
  - Let's say it takes time *c* per iteration.
    - Case 1: time c Case 2: time 2c  $\vdots$ Case i: time  $c \cdot i$  $\vdots$ Case n: time  $c \cdot n$

T(Case a) = C·a



# Average Case Time Complexity

The average case time complexity<sup>1</sup> of linear search is Θ(n).

<sup>&</sup>lt;sup>1</sup>Under these assumptions on the input!

### Note

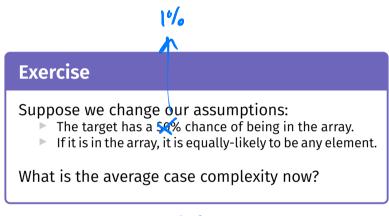
• Worst case time complexity is still useful.

Easier to calculate.

- Often same as average case (but not always!)
- Sometimes worst case is very important.
   Real time applications, time complexity attacks

# Note

- Hard to make realistic assumptions on input distribution.
- Example: linear search.
  - Is it realistic to assume t is in array?
  - If not, what is the probability that it is in the array?



0(n)

DSC 40B Theoretical Foundations II

#### Lecture 4 | Part 4

#### Average Case in Movie Problem

## **Recall: The Movie Problem**

- Given: an array movies of movie durations, and the flight duration t
- Find: two movies whose durations add to t.
   If no two movies sum to t, return None.

```
def find_movies(movies, t):
    n = len(movies)
    for i in range(n):
        for j in range(i + 1, n):
            if movies[i] + movies[j] == t:
                return (i, j)
    return None
```

# **Time Complexity**

Best case: Θ(1)

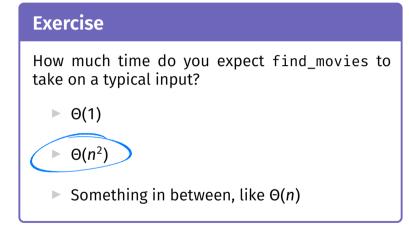
When the first pair of movies checked equals target.

• Worst case:  $\Theta(n^2)$ 

When no pair of movies equals target.

# "Average" Case?

- The best and worst cases are extremes.
- How much time is taken, typically?
  - That is, when the target pair is not the first checked nor the last, but somewhere in the middle.



### **The Movie Problem**

```
def find_movies(movies, t):
    n = len(movies)
    for i in range(n):
        for j in range(i + 1, n):
            if movies[i] + movies[j] == t:
                return (i, j)
    return None
```

# **Time Complexity**

- Best case: Θ(1)
- Worst case:  $\Theta(n^2)$
- Average case: Θ(?)

# **Step 0: Assume input distribution**

Suppose we are told that:

- There is a unique pair of movies that add to t.
- All pairs are equally likely.

## **Step 1: Determine the Cases**

• Case  $\alpha$ : the  $\alpha$ th pair checked sums to *t*.

Each pair of movies is a case.

▶ There are  $\binom{n}{2}$  cases.

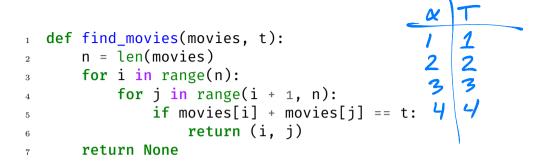
#### **Step 2: Case Probabilities**

- Assume: there is a unique pair that adds to t.
- **Assume**: all pairs are equally likely.

• Probability of any case: 
$$\frac{1}{\binom{n}{2}} = \frac{2}{n(n-1)}$$

## Step 3: Case Time

- How much time is taken for a particular case?
- Example, suppose the movies a and b sum to the target.
- How long does it take to find this pair?



#### Exercise

Roughly much time is taken (how many times does line 5 run) if the  $\alpha$ th pair checked sums to the target?  $\swarrow$ 

 $l = \frac{n(n+1)}{n} = G(n^2)$ **Step 4: Compute Expectation**  $T_{avy}(n) = \sum_{k=1}^{\binom{n}{2}} |P(case x) \times T(case \alpha) / k \cdot \binom{n}{2}$ N= 1 x = 1  $\widehat{\begin{pmatrix} n \\ 2 \end{pmatrix}} = \bigoplus(\frac{1}{N^2}) \times \bigoplus(n^4) = \bigoplus(n^2)$ 

### Average Case

- The average case time complexity of find\_movies is Θ(n<sup>2</sup>).
- Same as the worst case!

#### Note

- We've seen two algorithms where the average case = the worst case.
- Not always the case!
- Interpretation: the worst case is not too extreme.

DSC 40B Theoretical Foundations II

Lecture 4 | Part 5

**Expected Time Complexity** 

# **Example: Contrived Algorithm**

```
def wibble(n):
    # generate random number between 0 and n
    x = np.random.randint(0, n)
    if x == 0:
        for i in range(n):
            print('Unlucky!')
    else:
        print('Lucky!')
```

#### **Exercise**

How much time does wibble take on average?

## **Random Algorithms**

- ▶ This algorithm is *randomized*.
- ▶ The time it takes is also *random*.
- What is the expected time?

### Average Case vs. Expected Time

- With average case complexity, a probability distribution on inputs is specified.
- Now, the randomness is *in the algorithm itself*.
- Otherwise, the analysis is very similar.

### Step 1: Determine the cases

```
def wibble(n):
  x = np.random.randint(0, n)
  if x == 0:
     for i in range(n):
        print('Unlucky!')
  else:
     print('Lucky!')
Case 1: x == 0
Case 2: x != 0
```

# **Step 2: Determine case probabilities**

```
def wibble(n):
  x = np.random.randint(⊙, n)
  if x == ⊙:
     for i in range(n):
        print('Unlucky!')
  else:
        print('Lucky!')
P(Case 1) = 1/n
P(Case 2) = (n - 1)/n
```

## Step 3: Determine case times

```
def wibble(n):
  x = np.random.randint(⊙, n)
  if x == ⊙:
      for i in range(n):
           print('Unlucky!')
  else:
      print('Lucky!')
Case 1: Θ(n)
Case 2: Θ(1)
```

#### **Step 4: Compute expectation**

► Compute expected time:  $P(case 1) \times T(case 1) + P(case 2) \times T(case 2)$   $= \frac{1}{n} \times \Theta(n) + \frac{n-1}{n} \times \Theta(1)$   $= \Theta(1)$ 

# **Expected Time**

This was a contrived example.

- Some important algorithms involve randomness!
  - Quicksort
  - We'll see alg. for median with  $\Theta(n)$  expected time.

DSC 40B Theoretical Foundations II

Lecture 4 | Part 6

**Lower Bound Theory** 

## Imagine...

- You write a simple algorithm to solve a problem.
- You analyze time complexity and find it is  $\Theta(n^2)$ .
- You ask yourself: can I do better than  $\Theta(n^2)$ ?
- Or: What is the best time complexity possible?

## **Doing Better**

- How can you know what you don't know?
- You can argue that any algorithm for solving the problem must take at least a certain amount of time in the worst case.

## **Example: Minimum**

- Problem: Find minimum in array of length *n*.
- Any algorithm has to check all n numbers in the worst case.
  - Or else the number not checked could have been the smallest!
- Takes at least linear  $(\Omega(n))$  time.
  - **No algorithm** for the min can have worst case of < linear time.

#### Definition

A **theoretical lower bound** is a lower bound on the **worst-case** time complexity of **any algorithm** solving a particular problem.

#### Main Idea

No algorithm's worst case can possibly be better than theoretical lower bound.

#### **Loose Lower Bounds**

- $\Omega(\log n)$ ,  $\Theta(\sqrt{n})$  and  $\Theta(1)$  are also theoretical lower bounds for finding the minimum.
- But no algorithm can exist which has a worst case of  $\Theta(\log n)$ ,  $\Theta(\sqrt{n})$ , or  $\Theta(1)$ .
- ► This bound is **loose**. Not super useful.

### **Tight Lower Bounds**

- A lower bound is tight if there exists an algorithm with that worst case time complexity.
- That algorithm is (in a sense) optimal.

#### Definition

A **tight theoretical lower bound** for a problem is the **fastest** possible worst-case time complexity of any algorithm solving that problem.

### How to find a TLB

- Argument from completeness:
  - The algorithm might not be correct if it doesn't check k things, so the time is Ω(k).
- Argument from I/O:
  - If the output is an array of size k, time taken is Ω(k)
- More sophisticated arguments...

## Tight Bounds can be difficult to find

Often require sophisticated combinatorial arguments outside of the scope of DSC 40B.

## Assumptions make problems easier

The TLB for finding a minimum changes if we assume that the array is sorted.

# Exercise

Consider these two problems:

- 1. Find the min of a sorted array. <u>1</u>
- 2. Given a target t and a sorted array, determine whether t is in the array.  $\int_{\partial S} n$

Find tight theoretical lower bounds for each problem.

#### Main Idea

When coming up with an algorithm, first try to find a tight TLB. Then try to make an algorithm which has that worst-case complexity. If you can, it's **optimal**!

### **Practice makes perfect**

dsc40b.com/practice has a dozen more examples of finding theoretical lower bounds.

DSC 40B Theoretical Foundations II

Lecture 4 | Part 7

**Case Study: Matrix Multiplication** 

#### It's Important

- Matrix multiplication is a very common operation in machine learning algorithms.
- Estimate: 75% 95% of time training a neural network is spent in matrix multiplication.

#### Recall

If A is  $m \times p$  and B is  $p \times n$ , then AB is  $m \times n$ .

▶ The *ij* entry of *AB* is

$$(AB)_{ij} = \sum_{k=1}^{p} a_{ik} b_{kj}$$

#### Recall

$$(AB)_{ij} = \sum_{k=1}^{p} a_{ik} b_{kj}$$

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} \begin{pmatrix} 5 & -1 \\ 1 & 7 \\ -2 & -3 \end{pmatrix} = \begin{pmatrix} & & \\ & &$$

## Naïve Algorithm

This algorithm is relatively straightforward to code up.

```
def mmul(A, B):
    ,, ,, ,,
    A is (m \times p) and B is (p \times n)
    .....
    m, p = A.shape
    n = B.shape[1]
    C = np.zeros((m, n))
    for i in range(m):
         for j in range(n):
             for k in range(p):
                 C[i,j] += A[i,k] * B[k, j]
```

return C

## **Time Complexity**

• The naïve algorithm takes time  $\Theta(mnp)$ .

▶ If both matrices are  $n \times n$ , then  $\Theta(n^3)$  time.

#### Cubic!

### **Cubic Time Complexity**

The largest problem size that can be solved, if a basic operation takes 1 nanosecond.

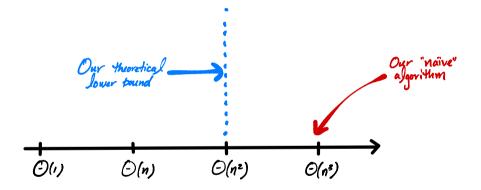
1 s	10 m	1 hr
1,000	6,694	15,326

### **The Question**

- Can we do better?
- How fast can we possibly multiply matrices?

### **Theoretical Lower Bound**

- ▶ If A and B are  $n \times n$ , C will have  $n^2$  entries.
- Each entry must be filled:  $\Omega(n^2)$  time.
- That is, matrix multiplication must take at least quadratic time.
- Is this bound tight? Can it be increased?

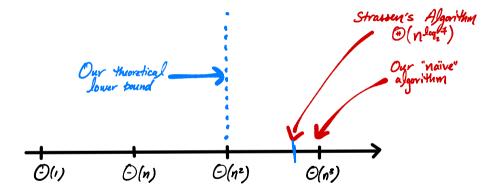


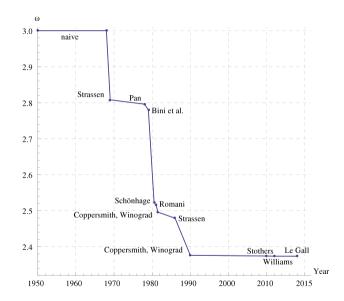
#### Strassen's Algorithm

Cubic was as good as it got...

...until Strassen, 1969.

Time complexity:  $\Theta(n^{\log_2 7}) = \Theta(n^{2.8073})$ 



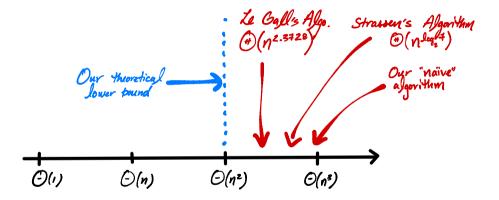


## Currently

The fastest<sup>2</sup> known matrix multiplication algorithm is due to Le Gall.

•  $\Theta(n^{2.3728639})$  time.

<sup>&</sup>lt;sup>2</sup>In terms of asymptotic time complexity.



### Interestingly...

- No one knows what the lowest possible time complexity is.
- ► It could be  $\Theta(n^2)$ !
- The "best" matrix multiplication algorithm is probably still undiscovered.

## Irony

There are many matrix multiplication algorithms.

How fast is numpy's matrix multiply?

## Irony

There are many matrix multiplication algorithms.

- How fast is numpy's matrix multiply?
- ► Θ(n<sup>3</sup>).

## Why?

- Strassen *et al.* have better asymptotic complexity.
- But much (much!) larger "hidden constants".
- Remember, which is better for small n: 999,999n<sup>2</sup> or n<sup>3</sup>?

## Optimization

Numpy, most others use highly optimized cubic time algorithms<sup>3</sup>

<sup>3</sup>The constant c in  $T(n) = cn^3 + ...$  is actually much less than 1, as can be verified by timing.

#### Main Idea

No one knows what the lowest possible time complexity of matrix multiplication is, and some algorithms are approaching  $\Theta(n^2)$ .

But most useful implementations take  $\Theta(n^3)$  time.